

Random experiment (doesn't know the outcome)

Different possible outcomes ξ which belong to sample space S of all possible outcomes

An event A is a subset of the sample space

Algebra of sets

\cup, \cap , complement \bar{A} (A^c), difference $A \setminus B = A \cap \bar{B}$

A and B disjoint if $A \cap B = \emptyset$ empty set.

Probability measure

$P(A)$ for $A \subseteq S$ gives probabilities to events, so that:

Three axioms are fulfilled

$P(A) \geq 0$

$P(S) = 1$ (sample space set of all outcomes)

$P(A \cup B) = P(A) + P(B)$ if $A \cap B = \emptyset$

consequences

proof.

$P(\bar{A}) = 1 - P(A)$ ($1 = P(S) = P(A \cup \bar{A}) = P(A) + P(\bar{A})$)

$P(\emptyset) = 0$

$P(A) \leq P(B)$ if $A \subseteq B$

$P(A) \leq 1$

$P(A \cup B) = P(A) + P(B) - P(A \cap B)$

$P(A \setminus B) = P(A) - P(A \cap B)$

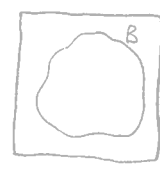
$P(\bigcup_{i=1}^n A_i) = \sum_{i=1}^n P(A_i)$ for A_i $i=1, \dots, n$ disjoint.

Conditional probability

of an event A given that we know that B has happened

DEFINITION (1)

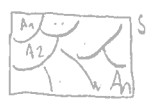
$P(A|B) = \frac{P(A \cap B)}{P(B)}$



$P(A \cap B) = P(A|B) \cdot P(B)$ follows from (1)

Total probability

Law of total probability



If A_1, \dots, A_n are disjoint and $\bigcup_{i=1}^n A_i = S$

$P(B) = \sum_{i=1}^n P(B|A_i)P(A_i)$ (if it is easier to calculate conditional probabilities)

Independence of events

A and B are independent if $P(A \cap B) = P(A) \cdot P(B)$

A_1, \dots, A_n are independent if $P(A_{i_1} \cap \dots \cap A_{i_n}) = P(A_{i_1}) \cdot \dots \cdot P(A_{i_n})$ for any selection of different indices $i_1, \dots, i_n \in \{1, \dots, n\}$

example dice

$\xi = \{1, 2, 3, 4, 5, 6\}$ Throw one dice $P = ?$ $P(1) = P(2) = P(3) = \dots = P(6) = \frac{1}{6}$ $P(A) = \frac{\#A}{\#S} = \frac{\text{nbr of members of } A}{6}$

$A = \{1, 2, 3\}$ $P(A|B) = P(\leq 3 | \text{odd}) = \frac{P(A \cap B)}{P(B)} = \frac{P(\{1, 3\})}{P(\{1, 3, 5\})} = \frac{2/6}{3/6} = \frac{2}{3}$

$B = \{1, 3, 5\}$

$\begin{matrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{matrix}$ intuitively $\frac{2}{3}$

Are A and B independent? $P(A \cap B) = P(A) \cdot P(B)$? NO!

2. Random Variables (Stochastic Variables)

Sample space S of all possible outcomes ξ of random experiment.
Probability measure P assigns probabilities $P(A)$ to events $A \subseteq S$

Random variable X

is a function from S to \mathbb{R} , $X: S \rightarrow \mathbb{R}$

$X(\xi)$ for $\xi \in S$ (random), which is random because ξ is random (the input/argument is random, not the function)
 $P(X \leq x) = P(\xi \in S : X(\xi) \leq x) \equiv F_X(x)$ called the cumulative distribution function, (CDF), for the random variable X for $x \in \mathbb{R}$

$0 \leq F_X(x) \leq 1$ (it is a probability)

$F_X(x_1) \leq F_X(x_2)$ if $x_1 \leq x_2$ (growing)

$\lim_{x \rightarrow \infty} F_X(x) = 1$ and $\lim_{x \rightarrow -\infty} F_X(x) = 0$

$P(a < X \leq b) = P(X \in]a, b]) = F_X(b) - F_X(a)$

Discrete random variables

A RV X is discrete if it has finitely or at most countably infinite many possible different values

probability mass function (PMF) $p_X(x) = P(X=x)$ for possible values x of X .

$0 \leq p_X(x) \leq 1$

$\sum_{\text{all } x} p_X(x) = 1$

$P(X \in A) = \sum_{x \in A} p_X(x)$

Continuous random variables

A RV X is continuous if $F_X(x)$ is (continuous) and differentiable.

probability density function (PDF) $f_X(x) = F_X'(x)$

$f_X(x) \geq 0$ (because $F_X(x)$ is increasing)

$\int_{-\infty}^{\infty} f_X(x) dx = F_X(\infty) - F_X(-\infty) = 1 - 0 = 1$

$P(X \in A) = \int_A f_X(x) dx$

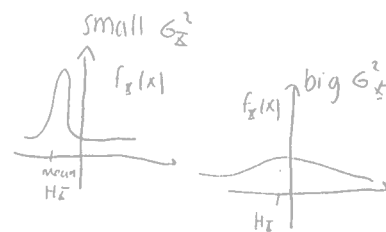
Mean, variance and other moments

$H_X = E(X)$ (expectation) the average value of X (center of gravity of the PDF and CDF)

$$\begin{cases} \sum_{\text{all } x} x p_X(x), & X \text{ discrete} \\ \int_{-\infty}^{\infty} x f_X(x) dx, & X \text{ continuous} \end{cases}$$

n^{th} moment of X $E(X^n) = \begin{cases} \sum_{\text{all } x} x^n p_X(x), & X \text{ discrete} \\ \int_{-\infty}^{\infty} x^n f_X(x) dx, & X \text{ continuous} \end{cases}$

Variance of X $\sigma_X^2 = \text{Var}(X) = E((X - H_X)^2) = \begin{cases} \sum_{\text{all } x} (x - H_X)^2 p_X(x) \\ \int_{-\infty}^{\infty} (x - H_X)^2 f_X(x) dx \end{cases}$



$\text{Var}(X) = E(X^2) - \mu_X^2$ follows from expanding, linearity etc.

examples of r.v. section 2.7

Discrete examples

Bernoulli distribution r.v. X with possible values $\{0,1\}$ $P(X=1) = P_X(1) = p$
 $P(X=0) = P_X(0) = 1-p$

Binomial distribution

Geometric distribution

Poisson distribution r.v. X with possible values $0,1,2,\dots$

$P_X(x) = e^{-\lambda} \frac{\lambda^x}{x!}$ for $x=0,1,2,\dots$ $\mu_X = \sigma_X^2 = \lambda$ (put it into the definitions)

Binomial distribution

with parameters n, p

Count the number of one's (1's) when we perform n independent Bernoulli random experiments.

$P(X=h) = P_B(h) = \binom{n}{h} p^h (1-p)^{n-h}$ (binomial theorem says sums to one) for $h=0, \dots, n$

Geometric distribution

The number X of the times we have to perform independent Bernoulli experiments to get the first 1. $P(X=h) = P_Z(h) = (1-p)^{h-1} p$ $h=1,2$

Continuous examples

• Uniform distribution over $[a,b]$

• Exponential distribution with parameter $\lambda > 0$

• Gamma distribution with parameter $\lambda > 0$ and $a > 0$

• Normal distribution $N(\mu, \sigma^2)$

(

)

8/10 Chapter 3 Multiple random variables

2-dim case

n-dim case.

$$\xi \in \mathcal{S}$$

(X, Y) random variable with values in \mathbb{R}^2 . (the same probability space $\mathcal{X}(\xi), \mathcal{Y}(\xi)$)

$$(\bar{X}_1, \dots, \bar{X}_n) \sim \mathbb{R}^n$$

cdf. $F_{\bar{X}}(x) = P(\bar{X} \leq x)$ ~~$F_{XY}(x, y) = P(\bar{X} \leq x, \bar{Y} \leq y)$~~

$$F_{\bar{Y}}(y) = P(\bar{Y} \leq y)$$

no information about their dependence

\bar{X} and \bar{Y} are independent if $P(\bar{X} \leq a, \bar{Y} \leq b) = P(\bar{X} \leq a) \cdot P(\bar{Y} \leq b)$
 $[-\infty, a] \times [-\infty, b]$

$$F_{\bar{X}, \bar{Y}}(x, y) = P(\bar{X} \leq x, \bar{Y} \leq y) = P(\bar{X} \leq x) \cdot P(\bar{Y} \leq y) = F_{\bar{X}}(x) \cdot F_{\bar{Y}}(y) \quad (\text{independent})$$

$$0 \leq F_{\bar{X}, \bar{Y}}(x, y) \leq 1$$

$$F_{\bar{X}, \bar{Y}}(x_1, y_1) \leq F_{\bar{X}, \bar{Y}}(x_2, y_2) \quad \text{for } x_1 \leq x_2, y_1 \leq y_2 \quad (\text{increasing in both variables})$$

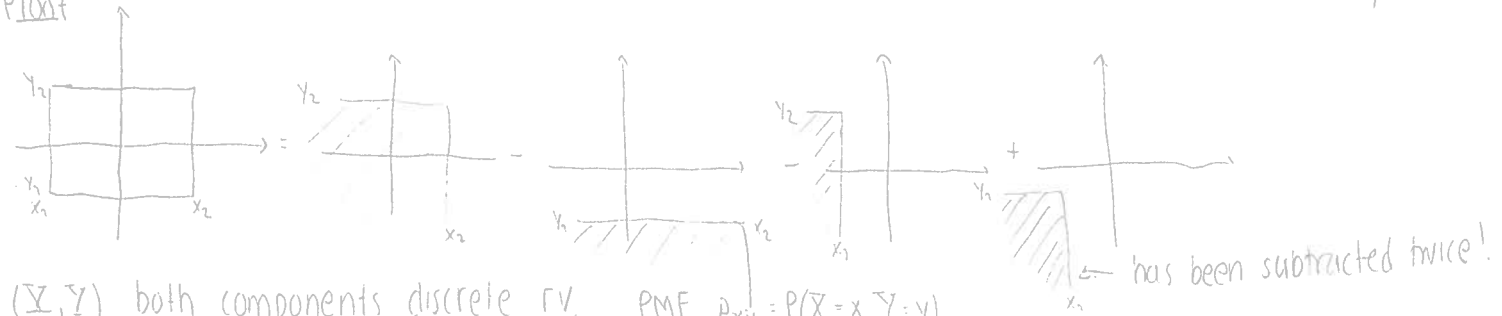
$$\lim_{x, y \rightarrow \infty} F_{\bar{X}, \bar{Y}}(x, y) = 1, \quad \lim_{x, y \rightarrow -\infty} F_{\bar{X}, \bar{Y}}(x, y) = 0$$

$$\lim_{x \rightarrow \infty} F_{\bar{X}, \bar{Y}}(x, y) = F_{\bar{Y}}(y), \quad \lim_{y \rightarrow \infty} F_{\bar{X}, \bar{Y}}(x, y) = F_{\bar{X}}(x)$$

have subtracted this one twice!

$$P(x_1 < \bar{X} \leq x_2, y_1 < \bar{Y} \leq y_2) = F_{\bar{X}, \bar{Y}}(x_2, y_2) - F_{\bar{X}, \bar{Y}}(x_1, y_2) - F_{\bar{X}, \bar{Y}}(x_2, y_1) + F_{\bar{X}, \bar{Y}}(x_1, y_1) \quad (P(x_1 < \bar{X} \leq x_2) = F_{\bar{X}}(x_2) - F_{\bar{X}}(x_1))$$

Proof



(\bar{X}, \bar{Y}) both components discrete rv. PMF $p_{\bar{X}, \bar{Y}} = P(\bar{X} = x, \bar{Y} = y)$

$$0 \leq p_{\bar{X}, \bar{Y}}(x, y) \leq 1$$

$$P(\bar{X} \in A, \bar{Y} \in B) = \sum_{(x, y) \in A \times B} p_{\bar{X}, \bar{Y}}(x, y)$$

(\bar{X}, \bar{Y}) both components continuous rv PDF $f_{\bar{X}, \bar{Y}}(x, y) = \frac{\partial^2 F_{\bar{X}, \bar{Y}}(x, y)}{\partial x \partial y}$

$$f_{\bar{X}, \bar{Y}}(x, y) \geq 0 \quad (\text{because the cdf is increasing in both arguments})$$

$$P(\bar{X} \in A, \bar{Y} \in B) = \iint_{(x, y) \in A \times B} f_{\bar{X}, \bar{Y}}(x, y) dx dy$$

$$f_{\bar{X}}(x) = \int_{-\infty}^{\infty} f_{\bar{X}, \bar{Y}}(x, y) dy, \quad f_{\bar{Y}}(y) = \int_{-\infty}^{\infty} f_{\bar{X}, \bar{Y}}(x, y) dx \quad (1)$$

$$\bar{X}, \bar{Y} \text{ independent} \Leftrightarrow f_{\bar{X}, \bar{Y}}(x, y) = f_{\bar{X}}(x) f_{\bar{Y}}(y)$$

proof (1)

$$f_{\bar{X}}(x) = \frac{d}{dx} F_{\bar{X}}(x) = \frac{d}{dx} P(\bar{X} \leq x) = \frac{d}{dx} F_{\bar{X}, \bar{Y}}(x, \infty) = \frac{d}{dx} P(\bar{X} \leq x, \bar{Y} < \infty) = \frac{d}{dx} \int_{-\infty}^{\infty} f_{\bar{X}, \bar{Y}}(\hat{x}, y) d\hat{x} dy = \int_{-\infty}^{\infty} f_{\bar{X}, \bar{Y}}(x, y) dy$$

example we get a Poisson(λ) distributed number N of lottery tickets. Each lottery ticket has winning chance p . What is the expected number of total wins on the N lottery tickets?

$$E[\text{total number of wins}] = \sum_{n=0}^{\infty} E[\text{total number of wins} | N=n] \cdot P(N=n) \dots = p\lambda$$

$\underbrace{\hspace{10em}}_{np} \quad \underbrace{\hspace{10em}}_{\frac{\lambda^n e^{-\lambda}}{n!}}$

conditional distributions

(X, Y) discrete conditional PMF $P_{X|Y}(x|y) = \frac{P_{XY}(x,y)}{P_Y(y)} = \frac{P(X=x, Y=y)}{P(Y=y)}$

$P(X=x) = \sum_{\text{all } y} P(X=x|Y=y) P(Y=y) = \sum_{\text{all } y} P_{X|Y}(x|y) P_Y(y)$

↑ total number of wins in earlier example $\binom{N}{x} p^x (1-p)^{N-x}$ according to (1)

$E[X] = \sum_{\text{all } y} E[X|Y=y] P_Y(y)$

(X, Y) continuous

$f_{X|Y}(x|y) \stackrel{\text{DEF}}{=} \frac{f_{X,Y}(x,y)}{f_Y(y)}$ motivation: $f_{X|Y}(x|y) = \frac{d}{dx} \lim_{\epsilon \rightarrow 0} P(X \leq x | Y \in [y-\epsilon, y]) = \frac{d}{dx} \lim_{\epsilon \rightarrow 0} \frac{P(X \leq x, Y \in [y-\epsilon, y])}{P(Y \in [y-\epsilon, y])}$

$= \frac{d}{dx} \lim_{\epsilon \rightarrow 0} \frac{F_{X,Y}(x,y) - F_{X,Y}(x,y-\epsilon)}{\epsilon} \frac{\epsilon}{F_Y(y) - F_Y(y-\epsilon)} = \frac{f_{X,Y}(x,y)}{f_Y(y)}$

$\rightarrow \frac{\partial^2}{\partial x \partial y} F(x,y) \quad \rightarrow \frac{1}{F'_Y(y)}$

$P(X \leq x) = \int_{-\infty}^{\infty} \int_{-\infty}^x f_{X|Y}(x'|y) f_Y(y) dy dx'$

$E[X|Y=y] = \int x f_{X|Y}(x|y) dx$

$E[X] = \int_{-\infty}^{\infty} E[X|Y=y] f_Y(y) dy$ proof $\int_{-\infty}^{\infty} E[X|Y=y] f_Y(y) dy = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x f_{X|Y}(x|y) dx f_Y(y) dy = \int_{-\infty}^{\infty} x (\int_{-\infty}^{\infty} f_{X,Y}(x,y) dy) dx = \int_{-\infty}^{\infty} x f_X(x) dx$ shown earlier today.

$= \int x f_X(x) dx = E[X]$ qed

N-variate normal (Gauss) distribution X n-dimensional rv.

$f_X(x) = \frac{1}{(2\pi)^{n/2} |\det K|^{1/2}} \exp(-\frac{1}{2} (x-\mu)^T K^{-1} (x-\mu))$ $\mu = \begin{bmatrix} E[X_1] \\ \vdots \\ E[X_n] \end{bmatrix}$ $K_{ij} = \text{Cov}(X_i, X_j)$

Covariance and variance (not 106-107 in the book)

$\text{Cov}(X, Y) = E[(X - \mu_X)(Y - \mu_Y)] = E[XY] - \mu_X E[Y] - \mu_Y E[X] + \mu_X \mu_Y = E[XY] - E[X]E[Y]$

$\text{Var}(X) = V[X] = E[(X - \mu_X)^2] = \text{Cov}[X, X] = E[X^2] - E[X]^2$ X and Y independent if $\text{Cov}[X, Y] = 0$.

X and Y independent $\Rightarrow \text{Cov}[X, Y] = 0$ since $E[XY] = \int \int xy f_X(x) f_Y(y) dx dy = E[X]E[Y]$

$\text{Corr}[X, Y] = \rho_{XY} = \frac{\text{Cov}[X, Y]}{\sqrt{V[X]V[Y]}}$, $|\rho_{XY}| \leq 1$ (big correlation ≈ 1) (small correlation ≈ 0)

$$\text{Cov}\left(\sum_{i=1}^n a_i \bar{X}_i, \sum_{j=1}^n b_j \bar{Y}_j\right) = [a_i, b_j \in \mathbb{R}] = \sum_{i=1}^n \sum_{j=1}^n a_i b_j \text{Cov}[\bar{X}_i, \bar{Y}_j]$$

$$\text{Var}\left[\sum_{i=1}^n a_i \bar{X}_i\right] = \text{Cov}\left[\sum_{i=1}^n a_i \bar{X}_i, \sum_{j=1}^n a_j \bar{X}_j\right] = \sum_{i=1}^n \sum_{j=1}^n a_i a_j \text{Cov}[\bar{X}_i, \bar{X}_j]$$

$$\text{Var}\left[\sum_{i=1}^n a_i \bar{X}_i\right] = \sum_{i=1}^n a_i^2 \text{Var}[\bar{X}_i] \text{ if } \bar{X}_1, \dots, \bar{X}_n \text{ independent}$$

29/10-10 Chapter 4 Functions of random variables

n-variate normal distribution

$$f_{\mathbf{X}}(\mathbf{x}) = \frac{1}{(2\pi)^{n/2} |\det \mathbf{K}|^{1/2}} \exp\left(-\frac{1}{2}(\mathbf{x}-\mathbf{H})^T \mathbf{K}^{-1}(\mathbf{x}-\mathbf{H})\right) \quad \text{PDF of n-variate normal distributed rv.}$$

$\mathbf{X} = (\bar{X}_1, \dots, \bar{X}_n), \mathbf{x} = (x_1, \dots, x_n)$

2-variate case

$$\mathbf{H} = \begin{bmatrix} E[\bar{X}_1] \\ E[\bar{X}_2] \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \mathbf{K} = \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix} = \begin{bmatrix} \text{Var}[\bar{X}_1] & \text{Cov}[\bar{X}_1, \bar{X}_2] \\ \text{Cov}[\bar{X}_1, \bar{X}_2] & \text{Var}[\bar{X}_2] \end{bmatrix} \quad |\rho| < 1$$

$$f_{\bar{X}_1, \bar{X}_2}(x_1, x_2) = \frac{1}{2\pi\sqrt{1-\rho^2}} \exp\left(-\frac{1}{2} [x_1 \ x_2] \frac{1}{1-\rho^2} \begin{bmatrix} 1 & -\rho \\ -\rho & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \frac{1}{2\pi\sqrt{1-\rho^2}} \exp\left(-\frac{x_1^2 - 2\rho x_1 x_2 + x_2^2}{2(1-\rho^2)}\right)$$

$$\begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 1 & -\rho \\ -\rho & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x_1^2 - \rho x_1 x_2 - \rho x_1 x_2 + x_2^2$$

$$f_{\bar{X}_1 | \bar{X}_2}(x_1 | x_2) = \frac{f_{\bar{X}_1, \bar{X}_2}(x_1, x_2)}{f_{\bar{X}_2}(x_2)} = \left[f_{\bar{X}_1}(x_1) = \int_{-\infty}^{\infty} f_{\bar{X}_1, \bar{X}_2}(x_1, x_2) dx_2 \right] = \int_{-\infty}^{\infty} \frac{1}{2\pi\sqrt{1-\rho^2}} \exp\left(-\frac{x_1^2 - 2\rho x_1 x_2 + x_2^2}{2(1-\rho^2)}\right) dx_2 =$$

$$= \frac{1}{2\pi\sqrt{1-\rho^2}} \int_{-\infty}^{\infty} \exp\left(-\frac{(x_1 - \rho x_2)^2}{2(1-\rho^2)}\right) \exp\left(-\frac{(1-\rho^2)x_2^2}{2(1-\rho^2)}\right) dx_2 = \frac{1}{\sqrt{2\pi}} e^{-x_1^2/2} \left(\int_{-\infty}^{\infty} e^{-\frac{x^2}{2}} dx = \sqrt{2\pi} \right) \frac{1}{\sqrt{2\pi}\sqrt{1-\rho^2}} \exp\left(-\frac{(x_1 - \rho x_2)^2}{2(1-\rho^2)}\right)$$

$$= \frac{1}{\sqrt{2\pi}\sqrt{1-\rho^2}} \exp\left(-\frac{x_1^2 - 2\rho x_1 x_2 + x_2^2}{2(1-\rho^2)}\right) \frac{1}{\sqrt{2\pi}} e^{-x_1^2/2} = \frac{1}{\sqrt{2\pi}\sqrt{1-\rho^2}} \exp\left(-\frac{(x_1 - \rho x_2)^2}{2(1-\rho^2)}\right) f_{N(x_2, 1-\rho^2)}$$

$Y = g(X)$ $g: \mathbb{R} \rightarrow \mathbb{R}$ X is continuous, g is invertible.

$$f_Y(y) = \frac{d}{dy} F_Y(y) = \frac{d}{dy} P(Y \leq y) = \frac{d}{dy} P(g(X) \leq y) = \frac{d}{dy} P(X \leq g^{-1}(y)) = \frac{d}{dy} F_X(g^{-1}(y)) = f_X(g^{-1}(y)) \frac{1}{g'(g^{-1}(y))}$$

$(Z, W) = j(X, Y)$ $j: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ X, Y continuous j invertible

$$f_{Z, W}(z, w) = f_{X, Y}(x, y) |j^{-1}(z, w)|$$

$$\begin{vmatrix} \frac{dx}{dz} & \frac{dx}{dw} \\ \frac{dy}{dz} & \frac{dy}{dw} \end{vmatrix} (j^{-1}(z, w))$$

$$f_{Z, W}(z, w) = \frac{\partial^2}{\partial z \partial w} P(z \leq Z, W \leq w) = \frac{\partial^2}{\partial z \partial w} \int \int_{\{j(x, y) \in [z, w] \times [z, w]\}} f_{X, Y}(x, y) dx dy$$

4.5 expectation $Y = g(X)$

$$E[Y] = E[g(X)] = \begin{cases} \int_{-\infty}^{\infty} g(x) f_X(x) dx, & X \text{ continuous} \\ \sum_{\text{all } x} g(x) p_X(x), & X \text{ discrete.} \end{cases}$$

$$E[g(X_1, \dots, X_n)] = \int_{-\infty}^{\infty} \dots \int_{-\infty}^{\infty} g(x_1, \dots, x_n) f_{X_1, \dots, X_n}(x_1, \dots, x_n) dx_1 \dots dx_n \quad \text{or } \int_{\mathbb{R}^n} g f_X$$
$$= \sum_{x_1} \dots \sum_{x_n} g(x_1, \dots, x_n) p_{X_1, \dots, X_n}(x_1, \dots, x_n)$$

$$E\left[\sum_{i=1}^n a_i X_i\right] = \sum_{i=1}^n a_i E[X_i] \quad E[g(X)h(Y)] = E[g(X)]E[h(Y)] \quad \text{if } X \text{ and } Y \text{ independent, } g, h, \text{ functions.}$$

$a_i \in \mathbb{R}$ X_i RV.

conditional expectation

$$E[Y|X=x] = \begin{cases} \int_{-\infty}^{\infty} y f_{Y|X}(y|x) dy & Y \text{ cont} \\ \sum_{-\infty}^{\infty} y f_{Y|X}(y|x) & Y \text{ discrete.} \end{cases}$$

$$E[Y|X] = \int_{-\infty}^{\infty} y f_{Y|X}(y|X) dy \quad (\text{keep } X \text{ random})$$

$$E[Y] = E[E[Y|X]] = \int_{-\infty}^{\infty} E[Y|X=x] f_X(x) dx$$

Jensens inequality

$E[g(x)] \geq g(E[x])$ for g a convex function.

example $E[X^2] \geq (E[X])^2$ x^2 convex

$E[|X|] \geq |E[X]|$ $|x|$ convex

Cauchy-Schwarz inequality

$$|E[XY]| \leq \sqrt{E[X^2]E[Y^2]} \quad | \langle x, y \rangle | \leq |x| \cdot |y|$$
$$\int fg \leq \sqrt{\int f^2 \int g^2}$$

TRANSFORMS!

Probability generating function

$$G_X(z) = E[z^X] = \sum_{x=0}^{\infty} z^x p_X(x) \quad \text{for } |z| < 1 \quad \text{for } \mathbb{N}\text{-valued rv. } X$$

$$G_X^{(n)}(z) \Big|_{z=0} = n! p_X(n) \quad \Rightarrow \quad p_X(n) = \frac{G_X^{(n)}(0)}{n!}$$

Moment generating function (MGF)

$$M_{\bar{X}}(t) = E[e^{t\bar{X}}] \begin{cases} \int_{-\infty}^{\infty} e^{tx} f_{\bar{X}}(x) dx, & \bar{X} \text{ continuous} \\ \sum_{\text{all } x} e^{tx} p_{\bar{X}}(x), & \bar{X} \text{ discrete} \end{cases}$$

$$M_{\bar{X}}(j\omega) = \psi_{\bar{X}}(\omega)$$

$$M_{\bar{X}}^{(n)}(t) \Big|_{t=0} = \frac{d^n}{dt^n} E[e^{t\bar{X}}] \Big|_{t=0} = E\left[\frac{d^n}{dt^n} e^{t\bar{X}}\right] \Big|_{t=0} = E[\bar{X}^n e^{t\bar{X}}] \Big|_{t=0} = E[\bar{X}^n]$$

$$= M_{\bar{X}}^{(n)}(0)$$

$$M_{\bar{X}, \bar{Y}}(t_1, t_2) = E[e^{t_1 \bar{X} + t_2 \bar{Y}}]$$

Characteristic function (CHF) $[j^2 = -1]$

$$\psi_{\bar{X}}(\omega) = E[e^{j\omega\bar{X}}] = \begin{cases} \int_{-\infty}^{\infty} e^{j\omega x} f_{\bar{X}}(x) dx \\ \sum_{\text{all } x} e^{j\omega x} p_{\bar{X}}(x) \end{cases}$$

$\omega \in \mathbb{R}$

always convergent! always well defined.

$$f_{\bar{X}}(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-j\omega x} \psi_{\bar{X}}(\omega) d\omega$$

$$\psi_{\bar{X}}^{(n)}(0) = \frac{d^n}{d\omega^n} E[e^{j\omega\bar{X}}] \Big|_{\omega=0} = E[(j\omega)^n e^{j\omega\bar{X}}] \Big|_{\omega=0} = E[(j)^n \bar{X}^n] \quad E[\bar{X}^n] = \frac{\psi_{\bar{X}}^{(n)}(0)}{j^n}$$

2-d Fourier transform

$$\psi_{\bar{X}, \bar{Y}}(\omega_1, \omega_2) = E[e^{j\omega_1 \bar{X} + j\omega_2 \bar{Y}}]$$

$$\bar{X} \text{ and } \bar{Y} \text{ independent} \iff F_{\bar{X}, \bar{Y}}(x, y) = F_{\bar{X}}(x) F_{\bar{Y}}(y) \iff f_{\bar{X}, \bar{Y}}(x, y) = f_{\bar{X}}(x) f_{\bar{Y}}(y)$$

$$\iff p_{\bar{X}, \bar{Y}}(\omega_1, \omega_2) = \psi_{\bar{X}}(\omega_1) \psi_{\bar{Y}}(\omega_2)$$

$$\iff M_{\bar{X}, \bar{Y}}(t_1, t_2) = M_{\bar{X}}(t_1) M_{\bar{Y}}(t_2)$$

example

$$\bar{X} = N(\mu, \sigma^2)$$

$$f_{\bar{X}}(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

$$\psi_{\bar{X}}(\omega) = \int_{-\infty}^{\infty} e^{j\omega x} f_{\bar{X}}(x) dx = \int_{-\infty}^{\infty} e^{j\omega x} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}} dx = \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu-j\omega\sigma^2)^2}{2\sigma^2}} dx \cdot e^{Hj\omega} e^{-\frac{\omega^2\sigma^2}{2}}$$

$$e^{Hj\omega} e^{-\frac{\omega^2\sigma^2}{2}}$$

1/11-10
 lids-Beta $\int_0^1 (\sin(\frac{1}{x}))^2 dx = \int_1^\infty \frac{\sin(x)^2}{x^2} dx = 0.673427 \pm 0.001$ (convergence error)
 $= 0.671563$ 0.673024 (simulation) $n=10^6$ simulations.

Chapter 4.

Section 4.9 Law of Large Numbers, CLT (central Limit Theorem)

X_1, X_2, \dots, X_n independent identically distributed (IID) random variables.

$\frac{1}{n} \sum_{i=1}^n X_i \rightarrow E[X_1], n \rightarrow \infty$

Chapter 5 Random processes

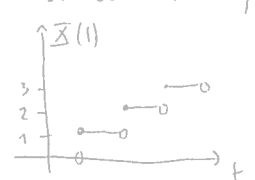
Random process (stochastic)

family of rv. indexed by time.

probability space

$\{X(t)\}_{t \in T}$ (bunch of rv) is a function $X: \Omega \times T \rightarrow \mathbb{R}$ defined on a sample space Ω and parameter set T .
 $= \{X(\omega, t)\}_{t \in T}$ Most commonly $T = \text{time}$, $T = \mathbb{R}$, $T = [0, \infty[$, $T = \mathbb{Z}$, $T = \mathbb{N}$, $T = [0, 1]$, $T = \{0, \dots, n\}$

ex) Poisson process

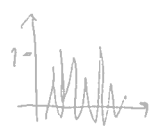


the value at each time t random (poisson)

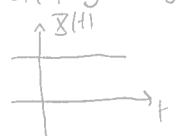
* continuous time + discrete time.

ex) completely "wild" white noise

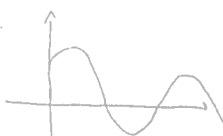
Each $X(t)$ is independent $N(0,1)$ -distributed.



ex) $X(t) = \xi$ a single $N(0,1)$ random variable



ex) $X(t) = A \cos(\omega t) + B \sin(\omega t)$ where $\omega \in \mathbb{R}$, A and B are zero-mean uncorrelated r.v. with variance σ^2 .



5.3 characterization of random processes

$F_{X(t)}(x) = P(X(t) \leq x)$ (very incomplete as a description of a process) no information about dependence among the rv

$F_{X(t_1), \dots, X(t_n)}(x_1, \dots, x_n) = P(X(t_1) \leq x_1, \dots, X(t_n) \leq x_n)$ for each choice of $n \in \mathbb{N}, t_1, \dots, t_n \in T$.
 finite dimensional distributions (fidi's)

PDF when process values are continuous: $f_{X(t_1), \dots, X(t_n)}(x_1, \dots, x_n) = \frac{\partial^n F(x_1, \dots, x_n)}{\partial x_1 \dots \partial x_n}$ (know everything about the process if this is known)

PMF discrete case

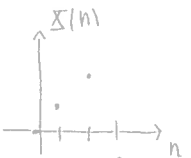
$P_{X(t_1), \dots, X(t_n)}(x_1, \dots, x_n) = P(X(t_1) = x_1, \dots, X(t_n) = x_n)$

ex) discrete time.

$X(n) = \sum_{i=1}^n Y_i$ for $n=0, 1, 2, \dots$ where $\{Y_i\}_{i=1}^\infty$ are IID rv.

$\{X(\omega_0, t)\}_{t \in T}$ for a fixed "typical" $\omega_0 \in \Omega$ is a realization of the process.

random walk



everytime one sees a picture of a process it is a realization of a process.

mean function

$$\mu_{\mathbf{z}(t)} = E[\mathbf{z}(t)]$$

these say interesting things about the process, but not everything.

Autocorrelation function

$$R_{\mathbf{z}}(s, t) = E[\mathbf{z}(s)\mathbf{z}(t)]$$

auto: because of covariance etc. between the process and itself.

Autocovariance function

$$K_{\mathbf{z}}(s, t) = \text{Cov}[\mathbf{z}(s), \mathbf{z}(t)]$$

$$K_{\mathbf{z}}(s, t) = R_{\mathbf{z}}(s, t) - \mu_{\mathbf{z}}(s)\mu_{\mathbf{z}}(t)$$

process values may differ, but not the law that defines the process

Stationary processes $(\mathbf{z}(t))_{t \in \mathbb{R}}$ is such that $[\mathbf{z}(t_1+h), \dots, \mathbf{z}(t_n+h)]$ same COF $[\mathbf{z}(t_1), \dots, \mathbf{z}(t_n)]$

finite dimensional distributions are invariant under time translations h .

Have to be able to calculate it's COF for all n -dimensional vectors to decide whether it is a stationary process.


Normal processes (Gaussian) $(\mathbf{z}(t))_{t \in T}$ process such that $(\mathbf{z}(t_1), \dots, \mathbf{z}(t_n))$ is n -dimensional normally distributed for each $t_1, \dots, t_n \in T$. That is:

$$\Psi_{\mathbf{z}(t_1), \dots, \mathbf{z}(t_n)}(\omega_1, \dots, \omega_n) = E[e^{j(\omega_1 \mathbf{z}(t_1) + \dots + \omega_n \mathbf{z}(t_n))}] = e^{j \sum_{i=1}^n \omega_i E[\mathbf{z}(t_i)] - \frac{1}{2} \sum_{i=1}^n \sum_{h=1}^n \omega_i \omega_h \text{Cov}[\mathbf{z}(t_i), \mathbf{z}(t_h)]}$$

$$f_{\mathbf{z}(t_1), \dots, \mathbf{z}(t_n)}(x_1, \dots, x_n) = \frac{1}{(2\pi)^{n/2} \sqrt{|\det K|}} e^{-\frac{1}{2}(x-H)^T K^{-1}(x-H)}$$

$$H = \begin{bmatrix} E[\mathbf{z}(t_1)] \\ \vdots \\ E[\mathbf{z}(t_n)] \end{bmatrix} \quad K = (\text{Cov}[\mathbf{z}(t_i), \mathbf{z}(t_h)])_{i,h}$$

ex) $\mathbf{z}(t)$

\uparrow single normal distr. cv. = normal process $\mathbf{z}(t) = A \cos(\omega t) + B \sin(\omega t) \quad A, B \sim N(0, \sigma^2)$  normal process

Ergodic processes $(\mathbf{z}(t))_{t \in \mathbb{R}}$

$\mathbf{z}(t)_{t \in \mathbb{R}}$ is a process such that $\lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} \mathbf{z}(t) dt = E[\mathbf{z}(0)]$. Assuming that $E[\mathbf{z}(t)] = E[\mathbf{z}(0)]$ is constant. (doesn't depend on t)

$$E[\mathbf{z}(t)] \leftarrow \frac{1}{n} \sum_{i=1}^n \mathbf{z}_i, \quad n \rightarrow \infty, \quad (\mathbf{z}_i)_{i=1}^n \text{ iid.}$$

important in practice because there is only one way of getting real results (only one world)

ex) If $\mathbf{z}(t)$ are iid. ("back on basic LLN")

WSS, weak stationary processes $(\mathbf{z}(t))_{t \in \mathbb{R}}$ such that $E[\mathbf{z}(t+h)] = E[\mathbf{z}(t)]$

very much easier for a process to be WSS than stationary $\text{Cov}[\mathbf{z}(s+h), \mathbf{z}(t+h)] = \text{Cov}[\mathbf{z}(s), \mathbf{z}(t)]$

most used in practice.
ex) $\mathbf{z}(t) = A \cos(\omega t) + B \sin(\omega t)$ where A, B are zero-mean, uncorrelated (zero-covariance) with common variance σ^2

$$\text{Cov}[\mathbf{z}(s), \mathbf{z}(t)] = [\text{autocovariance}] = \text{Cov}[A \cos(\omega s) + B \sin(\omega s), A \cos(\omega t) + B \sin(\omega t)] =$$

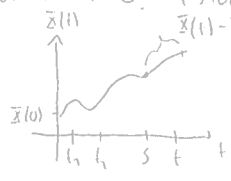
$$\underbrace{V[A] \cos(\omega s) \cos(\omega t)}_{\sigma^2} + \underbrace{0 + 0}_{\text{because of uncorrelation}} + \underbrace{V[B] \sin(\omega s) \sin(\omega t)}_{\sigma^2} = \sigma^2 \cos(\omega(s-t))$$

5/11-10 Processes with stationary independent increments - Levy processes

$\{\bar{X}(t)\}_{t \geq 0}$ $\bar{X}(0), \bar{X}(t_1) - \bar{X}(0), \bar{X}(t_2) - \bar{X}(t_1), \dots, \bar{X}(t_n) - \bar{X}(t_{n-1})$ independent for $0 < t_1 < \dots < t_n$ (independent increments)

$\bar{X}(t+h) - \bar{X}(t+s)$ same distribution as $\bar{X}(t) - \bar{X}(s)$ for $0 \leq s < t$ and $h > 0$. (stationary increments)

ex) Poisson process (ex) independent process



continuous time version of a discrete time random walk

$\bar{X}(n) = \sum_{i=1}^n Y_i$ for $n=0,1,2,\dots$ where $\{Y_i\}_{i=1}^{\infty}$ are iid r.v.'s.

Markov processes

$(\bar{X}(t))_{t \geq 0}$ $(\bar{X}(n))_{n \in \mathbb{N}}$ $P(\bar{X}(t_{n+1}) \leq x_{n+1} | \bar{X}(t_1) = x_1, \dots, \bar{X}(t_n) = x_n) = P(\bar{X}(t_{n+1}) \leq x_{n+1} | \bar{X}(t_n) = x_n)$

now the future depends on the history up to the value right now just right now

for $0 \leq t_1 < \dots < t_n < t_{n+1}$ (can skip previous part of the history) every stationary independent increment process is a Markov process.

ex) SITP

$P(\bar{X}(t_{n+1}) \leq x_{n+1} | \bar{X}(t_1) = x_1, \dots, \bar{X}(t_n) = x_n) = P(\underbrace{\bar{X}(t_{n+1}) - \bar{X}(t_n)}_{\text{independent of history}} + \underbrace{\bar{X}(t_n)}_{\substack{= x_n \\ \text{determined by } \bar{X}(t_n)}}) \leq x_{n+1} | \bar{X}(t_1) = x_1, \dots, \bar{X}(t_n) = x_n) = P(\bar{X}(t_{n+1}) \leq x_{n+1} | \bar{X}(t_n) = x_n)$

Markov chains

Discrete time Markov processes with discrete values

$F_{\bar{X}(t_1), \bar{X}(t_2)}(x_1, \dots, x_n) = F_{\bar{X}(t_1)}(x_1) \prod_{i=2}^n P(\bar{X}(t_i) \leq x_i | \bar{X}(t_{i-1}) = x_{i-1})$ (5.28)
 $F_{\bar{X}(t_1), \bar{X}(t_2)}(x_1, \dots, x_n) = \prod_{i=2}^n P(\bar{X}(t_i) \leq x_i | \bar{X}(t_{i-1}) \leq x_{i-1})$ Prob. 5.25

Solution

$F_{\bar{X}(t_1), \bar{X}(t_2)}(x_1, \dots, x_n) = P(\bar{X}(t_n) \leq x_n | \bar{X}(t_1) \leq x_1, \dots, \bar{X}(t_n) \leq x_n) \cdot P(\bar{X}(t_1) \leq x_1, \dots, \bar{X}(t_{n-1}) \leq x_{n-1})$

wrong $\neq P(\bar{X}(t_n) \leq x_n | \bar{X}(t_{n-1}) \leq x_{n-1}) P(\bar{X}(t_1) \leq x_1, \dots, \bar{X}(t_{n-1}) \leq x_{n-1})$

Because send $x_{n-1} \rightarrow \infty$ $P(\bar{X}(t_1) \leq x_1, \dots, \bar{X}(t_{n-2}) \leq x_{n-2}, \bar{X}(t_n) \leq x_n) = P(\bar{X}(t_n) \leq x_n) P(\bar{X}(t_1) \leq x_1, \dots, \bar{X}(t_{n-1}) \leq x_{n-1})$

5.5 discrete parameter Markov chains

$E = \{0, 1, \dots, N\} \Rightarrow$ finite matrix

$\{\bar{X}_n\}_{n=0}^{\infty}$ $\bar{X}_0, \bar{X}_1, \bar{X}_2, \dots$ possible values $E = \{0, 1, 2, \dots\} \Rightarrow$ infinite matrix.

$P(\bar{X}_{n+1} = j | \bar{X}_0 = i_0, \dots, \bar{X}_n = i_n) = P(\bar{X}_{n+1} = j | \bar{X}_n = i) = p_{ij}$ doesn't depend on n.

Time homogeneous

To characterize such processes we need two quantities

$P_0 = [P(\bar{X}_0 = 0) \ P(\bar{X}_0 = 1) \ \dots \ P(\bar{X}_0 = n)] = [P(\bar{X}_0 = i)]$; initial state probabilities

$P = (p_{ij})_{ij}$ transition matrix

$P = \begin{bmatrix} P_{00} & P_{01} & \dots \\ P_{10} & P_{11} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} = \begin{bmatrix} P(\bar{X}_{n+1} = 0 | \bar{X}_n = 0) & P(\bar{X}_{n+1} = 1 | \bar{X}_n = 0) & \dots \\ P(\bar{X}_{n+1} = 0 | \bar{X}_n = 1) & P(\bar{X}_{n+1} = 1 | \bar{X}_n = 1) & \dots \\ P(\bar{X}_{n+1} = 0 | \bar{X}_n = 2) & P(\bar{X}_{n+1} = 1 | \bar{X}_n = 2) & \dots \end{bmatrix}$

ex) $E = \{0, 1\}$ ($N=1$) $P = \begin{bmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{bmatrix} = \begin{bmatrix} P_{00} & P_{01} \\ P_{10} & P_{11} \end{bmatrix}$

tossing a coin for example

$X_n =$ "value" of coin after n 'th toss.
 $\sum_{j=1}^{\infty} P_{ij} = 1 \forall i$ (since some value has to be attained)
 $= \sum_{j=1}^{\infty} P(X_{n+1}=j | X_n=i) = 1 \forall i$, i.e., row sums are one.

$P^{(m)} = P(X_{n+m}=j | X_n=i)$ the m -step transition matrix.

$P^{(m)} = P^m$ proof for $m=2$ $P(X_{n+2}=j | X_n=i) = \frac{P(X_{n+2}=j, X_{n+1}=k, X_n=i)}{P(X_n=i)} = \sum_{k=0}^{\infty} \frac{P(X_{n+2}=j, X_{n+1}=k, X_n=i)}{P(X_n=i)}$ (law of total probability)

$= \sum_{k=0}^{\infty} \frac{P(X_{n+2}=j, X_{n+1}=k, X_n=i)}{P(X_{n+1}=k, X_n=i)} \cdot \frac{P(X_{n+1}=k, X_n=i)}{P(X_n=i)}$
 $= \sum_{k=0}^{\infty} \frac{P(X_{n+2}=j | X_{n+1}=k, X_n=i)}{P_{kj}} \cdot \frac{P(X_{n+1}=k | X_n=i)}{P_{ik}} = \sum_{k=0}^{\infty} P_{kj} P_{ik} = (P^2)_{ij}$

Chapman-Holmogorov theorem

Correct version of formula 5.28

$P(X_0=i_0, \dots, X_n=i_n) = P(X_0=i_0) \prod_{k=1}^n P(X_k=i_k | X_{k-1}=i_{k-1})$ (Markov)

Proof: $P(X_0=i_0, \dots, X_n=i_n) = P(X_n=i_n | X_0=i_0, \dots, X_{n-1}=i_{n-1}) P(X_0=i_0, X_1=i_1, \dots, X_{n-1}=i_{n-1}) = P(X_n=i_n | X_{n-1}=i_{n-1}) P(X_0=i_0, \dots, X_{n-1}=i_{n-1})$

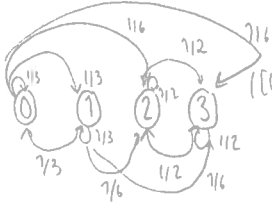
$= \dots = P(X_n=i_n | X_0=i_0) = P_{ij}^{(n)}$ (in n steps move from i to j)

$P(X_n=j) = \sum_{i=0}^{\infty} P(X_n=j | X_0=i) P(X_0=i) = \sum_{i=0}^{\infty} P_{ij}^{(n)} p(0)_i = (P^{(n)} p(0))_j$

$P^{(n)} = [P(X_n=0), P(X_n=1), \dots] = P^{(n)} p(0)$

ex) $E = \{0, 1, 2, 3\}$ $p(0) = \dots$ (starting distribution) $(X_n)_{n=0}^{\infty}$

$P = \begin{bmatrix} 1/3 & 1/3 & 1/6 & 1/6 \\ 1/3 & 1/3 & 1/6 & 1/6 \\ 0 & 0 & 1/2 & 1/2 \\ 0 & 0 & 1/2 & 1/2 \end{bmatrix}$ qualitatively different to 0,1



(Coin tossing behaviour) $2/3$

one can never get back to zero and one when once left.

transient (eventually you can move from them and never come back)
 $\{0, 1, 2, 3\}$
 recurrent (can never escape from them)

Classification of states

$T_j =$ the number of steps to the first visit of state j given starting at state j at time 0

j is RECURRENT if $P(T_j < \infty) = 1$

j is TRANSIENT if $P(T_j < \infty) < 1$

$i \rightarrow j$ if $P_{ij}^{(n)} = P(X_n=j | X_0=i) > 0$ for some n . j is ACCESSIBLE from i .

$i \leftrightarrow j$ if $i \rightarrow j$ and $j \rightarrow i$ i and j communicate.

ex) $2 \leftrightarrow 3$
 $0 \rightarrow 1, 2, 3$
 $1 \rightarrow 0, 2, 3$
 $2 \rightarrow 0, 1$
 $3 \rightarrow 0, 1$

11/10-70

Markov chains (special case of Markov process)

state space of possible values $E = \{0, 1, 2\}$ $E = \{0, 1, \dots, N\}$

$(X_n)_{n=0}^{\infty}$ random process with values in E possesses the Markov property.

$P(X_{n+1} = x_{n+1} | X_n = x_n, \dots, X_0 = x_0) = P(X_{n+1} = x_{n+1} | X_n = x_n)$

Initial distribution $p(0) = [P(X_0=0) \ P(X_0=1) \ \dots]$

Time homogeneity $P(X_{n+1}=j | X_n=i)$ doesn't depend on n . (the probability law of how to move around doesn't change)

Transition probability matrix

$$P = \begin{bmatrix} P(X_{n+1}=0 | X_n=0) & P(X_{n+1}=1 | X_n=0) & \dots \\ P(X_{n+1}=0 | X_n=1) & P(X_{n+1}=1 | X_n=1) & \dots \\ P(X_{n+1}=0 | X_n=2) & P(X_{n+1}=1 | X_n=2) & \dots \\ \vdots & \vdots & \ddots \end{bmatrix}$$

computer problem

$E = \{0, 1, 2\}$ $p(0) = [1 \ 0 \ 0]$ starts in 0 for sure.

$$P = \begin{bmatrix} 1/2 & 1/3 & 1/6 \\ 0 & 2/3 & 1/3 \\ 0 & 0 & 1 \end{bmatrix}$$

(geometric distribution)



aperiodic (not periodic, $p=1$)

$T = \min \{n \in \mathbb{N} : X_n = 2\}$

$E(T) = 4$

average in moving from zero
average in moving from 1 to 2

$\frac{2}{3} \cdot (2+3) + \frac{1}{3} \cdot 2$ (different ways) added up.

simulate T n times with result T_1, \dots, T_n

$\bar{T} \pm 2 \cdot s_T$ (99%-confidence interval)

states 0,1 transient - "temporary"

state 2 recurrent, even absorbing.

classification of states

$T_i = \min \{n \geq 1 : X_n = i \text{ given } X_0 = i\}$

State i is TRANSIENT if $P(T_i = \infty | X_0 = i) > 0$ (might have to wait infinitely long to get back to i) $\Leftrightarrow P(T_i < \infty | X_0 = i) < 1$ (temporary)

RECURRENT if $P(T_i < \infty | X_0 = i) = 1$

ABSORBING if $\{P(X_{n+1}=j | X_n=i) = 0 \text{ for } j \neq i$

(special of recurrent) $\{P(X_{n+1}=i | X_n=i) = 1$

$\leftrightarrow j$ is 'accessible from i if $P(X_n=j | X_0=i) > 0$ for some n .

i and j communicate if $i \rightarrow j$ and $j \rightarrow i$

State i is periodic with period p if $\gcd \{n \geq 1 : P_{ii}(n) = P\{X_n=i | X_0=i\} > 0\} = p > 1$

ex) periodic chain. $E = \{0, 1\}$ $p = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$



$\{4, 6, 8, \dots\}$
 $\gcd \{n \geq 1 : P(X_n=i | X_0=i) > 0\} = 2$ for $n=0, 1$.

$X(t_i) = X_{t_i}$

PMF $p_{X(t_1), X(t_2)} = P(X(t_1)=x_1, \dots, X(t_2)=x_n) \quad 0 \leq t_1 \leq \dots \leq t_n$

$= \frac{P(X(t_1)=x_1, \dots, X(t_n)=x_n)}{P(X(t_1)=x_1, \dots, X(t_{n-1})=x_{n-1})} \cdot P(X(t_1)=x_1, \dots, X(t_{n-1})=x_{n-1}) = P(X(t_n)=x_n | X(t_{n-1})=x_{n-1}) \cdot P(X(t_1)=x_1, \dots, X(t_{n-1})=x_{n-1})$

$= \dots = P(X(t_n)=x_n | X(t_{n-1})=x_{n-1}) \cdot P(X(t_{n-1})=x_{n-1} | X(t_{n-2})=x_{n-2}) \cdot \dots \cdot P(X(t_1)=x_1, X(t_{n-1})=x_{n-1})$

$= \dots = P(X(t_n)=x_n | X(t_{n-1})=x_{n-1}) \cdot P(X(t_{n-1})=x_{n-1} | X(t_{n-2})=x_{n-2}) \cdot \dots \cdot P(X(t_1)=x_1)$

$(P^{t_n-t_{n-1}})_{x_{n-1} x_n} \times (P^{t_{n-1}-t_{n-2}})_{x_{n-2} x_{n-1}} \times \dots \times (P^0)_{x_1}$

p. 5.88 in the book

stationary distribution \hat{p} given by $\hat{p} = \hat{p}P$
 \hat{p} probability distribution

ex) $P = \begin{bmatrix} 1-\alpha & \alpha \\ \beta & 1-\beta \end{bmatrix}$ $\alpha, \beta \in [0,1]$ real numbers $E = \{0,1\}$

$\begin{bmatrix} p_0 & p_1 \end{bmatrix} \begin{bmatrix} 1-\alpha & \alpha \\ \beta & 1-\beta \end{bmatrix} = \begin{bmatrix} p_0 \\ p_1 \end{bmatrix}$

$$\begin{cases} (1-\alpha)p_0 + \beta p_1 = p_0 \\ \alpha p_0 + (1-\beta)p_1 = p_1 \\ p_0 + p_1 = 1 \end{cases}$$

overdetermined - reason why probability distribution doesn't always exist.
 may or may not exist, depends on P.

$\begin{cases} p_0, p_1 \geq 0 \\ p_0 + p_1 = 1 \end{cases}$ } probability distribution

$$\begin{cases} -\alpha p_0 + \beta p_1 = 0 \\ \alpha p_0 - \beta p_1 = 0 \\ p_0 + p_1 = 1 \end{cases}$$

$\alpha = \beta = 0 \Rightarrow p_0 + p_1 = 0 \quad p_0 = p \quad p_1 = 1-p \quad \forall p \in [0,1]$

$\alpha = 0, \beta > 0 \Rightarrow p_0 = 1, p_1 = 0$

$\alpha > 0, \beta = 0 \Rightarrow p_0 = 0, p_1 = 1$

$\alpha, \beta > 0 \quad p_0 = \frac{\beta}{\alpha} p_1 \quad (\frac{\beta}{\alpha} + 1)p_1 = 1 \quad p_1 = \frac{1}{\frac{\beta}{\alpha} + 1} = \frac{\alpha}{\alpha + \beta} \quad p_0 = \frac{\beta}{\alpha + \beta}$

If the chain is started according to the stationary distribution then it will always have the stationary distribution.

$p(n) = [P(\bar{X}_n=0) \quad P(\bar{X}_n=1) \quad \dots] = \hat{p}$

proof: $p(n) = p(0)P^n = \hat{p}P^n = (\hat{p}P)P^{n-1} = \hat{p}P^{n-1} = \dots = \hat{p}$

$P(\bar{X}_n=i) \rightarrow \hat{p}_i$ as $n \rightarrow \infty$ (sort of a steady state)  volt-meter.

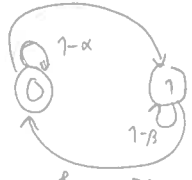
In the book
 $\lim_{n \rightarrow \infty} P^n = \hat{p} = \begin{bmatrix} \hat{p}_0 \\ \hat{p}_1 \\ \vdots \end{bmatrix}$

Proof that Hsu's formula implies Albin's

$P(\bar{X}_n=i) = [P(0)P^n]_i \rightarrow (P(0) \begin{bmatrix} \hat{p}_0 \\ \hat{p}_1 \\ \vdots \end{bmatrix})_i = (P(0) \begin{bmatrix} \hat{p}_1 & \hat{p}_2 & \hat{p}_3 \\ \hat{p}_1 & \hat{p}_2 & \hat{p}_3 \\ \vdots & \vdots & \vdots \end{bmatrix})_i = [\hat{p}]_i$

$T_i = \min\{n > 1 : \bar{X}_n = i \text{ if } \bar{X}_0 = i\}$
 $E[T_i] = \frac{1}{\text{the longer time it goes in coming back to } i \text{ is dependent of how long it is to be in } i}$

ex) $\hat{p} = \begin{bmatrix} \frac{\beta}{\alpha + \beta} & \frac{\alpha}{\alpha + \beta} \end{bmatrix}$ $E = \{0,1\}$ $P = \begin{bmatrix} 1-\alpha & \alpha \\ \beta & 1-\beta \end{bmatrix}$ $\alpha, \beta \in]0,1[\in \mathbb{R}$



$E[T_0]$ = expected value of smallest time greater than one that you come back to zero when starting in zero

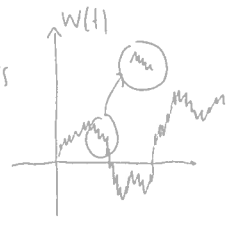
$E[T_0] = 1 \cdot (1-\alpha) + \alpha(1 + \frac{1}{\beta}) = \frac{\alpha + \beta}{\beta} = \frac{1}{\hat{p}_0}$
 ↑
 geometric distribution

2/11-10) Final words about Markov chains

Poisson process

Wiener process (Brownian motion) - most important process in the world.

Wiener process
continuous process
but nowhere
differentiable



- $w(0) = 0$ starts at zero
- independent increments $w(t_1), w(t_2) - w(t_1), \dots, w(t_n) - w(t_{n-1})$ independent for $0 \leq t_1 \leq \dots \leq t_n$
- stationary increments with $w(t+s) - w(s) \sim N(0, \sigma^2 t)$
- continuous sample paths.

$$\begin{cases} E[w(t)] = 0 \\ \text{Cov}[w(s), w(t)] = \underbrace{V[w(t)]}_{\sigma^2} \min(s, t) \end{cases}$$

$\{w(t)\}_{t \geq 0}$ normal process (Gaussian process)

DEF: $\{X(t)\}_{t \in T}$ normal iff $\Psi_{X(t_1), \dots, X(t_n)}(\omega_1, \dots, \omega_n) = E[e^{i \sum_{i=1}^n \omega_i X(t_i)}] = e^{i \omega^T \mu - \frac{1}{2} \omega^T K \omega}$

Thus $\{X(t)\}_{t \in T}$ normal $\iff \sum_{i=1}^n \omega_i X(t_i)$ is one-dimensional normal

normally distributed for any $n \in \mathbb{N}, \omega_1, \dots, \omega_n \in \mathbb{R}, t_1, \dots, t_n \in T$

$E[e^{i \omega^T X(t)}] = e^{i \omega^T \mu - \frac{1}{2} \omega^T K \omega}$ characteristic function of normal distribution

$K = \text{Cov}(X(t_n), X(t_1))_{n,1}$
 $\omega = \begin{bmatrix} \omega_1 \\ \vdots \\ \omega_n \end{bmatrix}$
 $\mu = \begin{bmatrix} E[X(t_1)] \\ \vdots \\ E[X(t_n)] \end{bmatrix}$

$$\sum_{i=1}^n \omega_i w(t_i) = \omega_n (w(t_n) - w(t_{n-1})) + (\omega_{n-1} + \omega_n) (w(t_{n-1}) - w(t_{n-2})) + \dots + (\omega_1 + \dots + \omega_n) w(t_1)$$

$t_1 \leq \dots \leq t_n$
 $t_0 = 0$

one dimensional normal distributed.
normally distributed

Reason that $(w(t))_{t \geq 0}$ is so important is that the non-existing derivative $(w'(t))_{t \geq 0}$ is continuous (completely) white noise!

Verify this empirically $\left(\frac{w(t+\Delta) - w(t)}{\Delta} \right)_{t \geq 0}$ for very small Δ .



noise that disturbs electrical signals for example.

$$K_{w'}(s, t) = \text{Cov}[w'(s), w'(t)] = \sigma^2 \delta(t-s)$$

ex) Nobel prize awarded Black-Scholes model for stock-price.

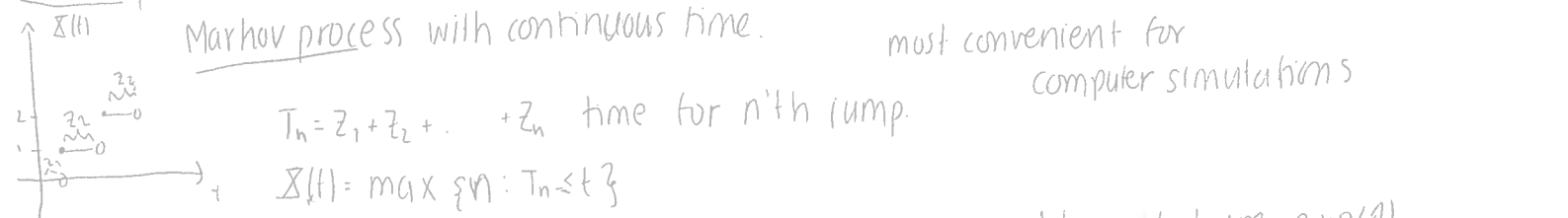
$$(S(t))_{t \geq 0} \quad \frac{dS(t)}{dt} = S(t) \frac{dw(t)}{dt}, \quad S(0) = S_0 \quad S'(t) = S(t) w'(t)$$

Wiener process is Markov process

$$P(w(t_{n+1}) \leq x_{n+1} | w(t_n) = x_n, \dots, w(t_1) = x_1) = P(w(t_{n+1}) - w(t_n) \leq x_{n+1} - x_n | w(t_n) = x_n, \dots, w(t_1) = x_1) = P(w(t_{n+1}) \leq x_{n+1} | w(t_n) = x_n)$$

Poisson process discrete valued process, continuous time $(X(t))_{t \geq 0}$

Markov process with continuous time. most convenient for computer simulations



$T_n = z_1 + z_2 + \dots + z_n$ time for n'th jump.

$X(t) = \max \{n : T_n \leq t\}$

$(z_n)_{n=1}^{\infty}$ interarrival time, independent, positive random variables that are $\exp(\lambda)$ distributed.

Renewal process is such process where $(z_n)_{n=1}^{\infty}$ can be any sequence of iid positive random variables.

Renewal process = counting process (counting arrivals)

Alternative definition Poisson process $(X(t))_{t \geq 0}$ with intensity λ is given by:

- $X(0) = 0$
- $X(t)$ has independent increments.
- $X(t+s) - X(s)$ is $\text{Poi}(\lambda t)$ -distributed.

Another alternative definition of Poisson process $(X(t))_{t \geq 0}$ with intensity λ is

- $X(0) = 0$
- $X(t)$ independent increments
- $X(t)_{t \geq 0}$ integer valued. (IN-valued), non-decreasing with $P(X(t+\Delta t) - X(t) = 0) = 1 - \lambda \Delta t + O(\Delta t)$

$P(X(t+\Delta t) - X(t) = 1) = \lambda \Delta t + O(\Delta t)$

$P(X(t+\Delta t) - X(t) \geq 2) = O(\Delta t)$

$E[X(t)] = E\{X(n)\} t = \lambda t$

$\text{cov}[X(s), X(t)] = V[X(t)] \min(s, t) = \lambda \min(s, t)$

Note: $Y(t) = W(t) + \sigma^2 t$

$E[Y(t)] = 0 + \sigma^2 t$

$\text{cov}[Y(s), Y(t)] = \text{cov}[W(s), W(t)] = \sigma^2 \min(s, t)$

If $(X_1(t))_{t \geq 0}$ and $(X_2(t))_{t \geq 0}$ are independent Poisson processes with intensity parameters λ_1 and λ_2 respectively, then $Y(t) = X_1(t) + X_2(t)$ is a Poisson process with intensity $\lambda_1 + \lambda_2$.

$M_{X_1(t)}(s) = E[e^{sX_1(t)}] = E[e^{sP_{\lambda_1}(t)}] = e^{\lambda_1(s-1)t}$

$M_{X_2(t)}(s) = \dots = e^{\lambda_2(s-1)t}$

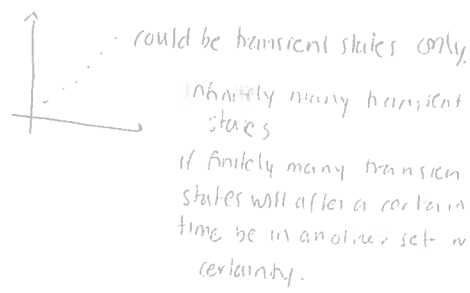
$M_{X_1(t)+X_2(t)}(s) = E[e^{s(X_1(t)+X_2(t))}] = E[e^{sX_1(t)}] E[e^{sX_2(t)}] = e^{\lambda_1(s-1)t} e^{\lambda_2(s-1)t} = e^{(\lambda_1+\lambda_2)(s-1)t}$

can use characteristic fcn to show that a sum of two Poisson is Poisson!

Final words about Markov chains

$$E = \{0, 1, 2, \dots\} = T \cup \left(\begin{array}{c} \text{communicating} \\ \text{recurrent} \\ \text{states 1} \end{array} \right) \overset{\text{not communicating}}{\cup} \left(\begin{array}{c} \text{communicating} \\ \text{recurrent} \\ \text{states 2} \end{array} \right) \dots \cup \left(\begin{array}{c} \text{communicating} \\ \text{recurrent} \\ \text{states h} \end{array} \right) \cup \left(\begin{array}{c} \text{transient} \\ \text{states} \end{array} \right)$$

(absorbing state 1) $\cup \dots \cup$ (absorbing state m) can't get out of any of the sets except the transient set.



Stationary distribution

$$\hat{p} = \hat{p} P \quad \lim_{n \rightarrow \infty} P(\bar{X}_n = i) = \lim_{n \rightarrow \infty} P(\bar{X}_n = i | \bar{X}_0 = j) = (\hat{p})_i = \frac{1}{E[T_i]}$$

For a chain where all states communicate (irreducible chain) and are aperiodic. (all states must have the same period)

ex) $E = \{0, 1\}$ $P = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ can start it randomly, otherwise it is not random

$$\hat{p} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \end{bmatrix} \quad \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \end{bmatrix} \quad \hat{p}(1) = [1 \ 0]$$

$$\lim_{n \rightarrow \infty} P(\bar{X}_n = i) = \frac{1}{2} \quad P(\bar{X}_{2n} = 0) = 1 \quad P(\bar{X}_{2n+1} = 0) = 0$$

it's periodic - that's why this isn't true.

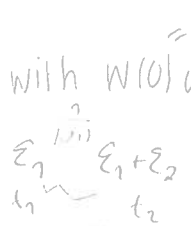
18/11-10

Computer problem 3

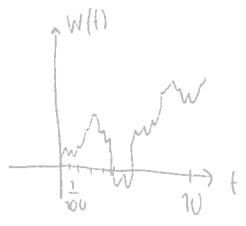
Wiener process $\{W(t)\}_{t \geq 0}$ independent stationary increment process with $W(0) = 0$ and

$$W(t+s) - W(s) \sim N(0, \sigma^2 t) \quad \sigma^2 = 1$$

Find $\text{cov}(\Delta_\varepsilon(s), \Delta_\varepsilon(t))$ where $\Delta_\varepsilon(t) = \frac{W(t+\varepsilon) - W(t)}{\varepsilon} \quad t \geq 0$ plot $\Delta_\varepsilon(t)$



plot $W(t)$



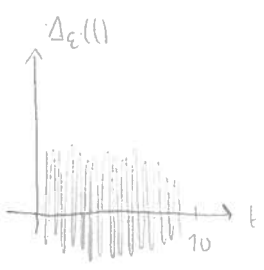
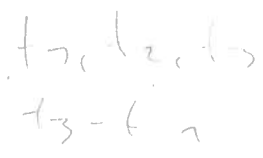
$$W\left(\frac{i}{100}\right) = \sum_{j=1}^i \varepsilon_j \quad \varepsilon_j \sim N\left(0, \frac{1}{100}\right)$$

Need a vector of ε 's

$$W = [0, \varepsilon_1, \varepsilon_1 + \varepsilon_2, \dots, \sum_{i=1}^{1000} \varepsilon_i]$$

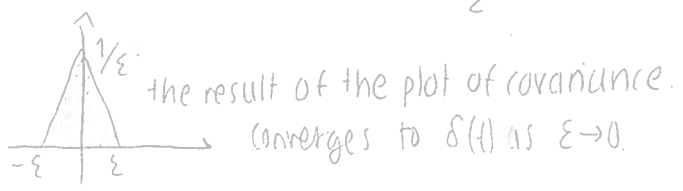
$$W_{t+\varepsilon} = [\varepsilon_1, \varepsilon_1 + \varepsilon_2, \dots, \sum_{j=1}^{1000} \varepsilon_j]$$

$$\frac{W_{t+\varepsilon} - W}{1/100}$$



$$\text{Cov}[\Delta_\varepsilon(s), \Delta_\varepsilon(t+s)] = \frac{\text{Cov}[W(s+\varepsilon) - W(s), W(t+s+\varepsilon) - W(t+s)]}{\varepsilon^2} = \frac{\min(s+\varepsilon, t+s+\varepsilon) - \min(s+\varepsilon, t+s) - \min(s, t+s+\varepsilon) + \min(s, t+s)}{\varepsilon^2}$$

$$\text{Cov}[W(s), W(t+s)] = \min[s, t+s]$$



5.8 Martingales one of the most important classes of processes

$\{\bar{X}_n\}_{n=0}^{\infty}$ discrete time stochastic process

$E[\bar{X}_{n+1} | \bar{X}_1 = x_1, \dots, \bar{X}_n = x_n] = \bar{X}_n$ DEFINITION OF A MARTINGALE PROCESS.

wants to model a fair game
is exactly fair.

ex) $\bar{Y}_1, \bar{Y}_2, \dots$ independent, zero-mean r.v.'s

$E[\bar{X}_{n+1} | \bar{X}_1, \dots, \bar{X}_n] = \bar{X}_n$
 $g(\bar{X}_1, \dots, \bar{X}_n) = \bar{X}_n$
 $E[\bar{X}_{n+1} | F_n] = \bar{X}_n$

$\bar{X}_n = \sum_{i=1}^n \bar{Y}_i$ is a martingale (the most basic one)

each \bar{X} a sum of \bar{Y} 's.

↑ accumulated gain after n turns of the game.

$E[\bar{X}_{n+1} | \bar{X}_1 = x_1, \dots, \bar{X}_n = x_n] = E[\bar{Y}_{n+1} + \sum_{i=1}^n \bar{Y}_i | \bar{Y}_1 = x_1, \bar{Y}_1 + \bar{Y}_2 = x_2, \dots, \sum_{i=1}^n \bar{Y}_i = x_n] = 0 + x_n = x_n$

↑ independent of $\bar{Y}_1, \dots, \bar{Y}_n$

can forget about the past, because the r.v are independent

The process that is zero all the time is also a martingale but not a very interesting one.

Conditioning (continued)

$E[\bar{Y} | \bar{X} = x] = g(x)$

$\int_{-\infty}^{\infty} y f_{\bar{Y}|\bar{X}}(y|x) dy = g(x)$

$E[\bar{Y} | \bar{X}] = g(\bar{X})$ more convenient

$f_{\bar{Y}, \bar{X}}(y, x)$ when they are continuous.

because the notation is more compact.

means the same thing but \bar{X} is not determined yet.

$E[\bar{Y} | \bar{X}_1 = x_1, \dots, \bar{X}_n = x_n] = g(x_1, \dots, x_n)$

$E[\bar{Y} | \bar{X}_1, \dots, \bar{X}_n] = g(\bar{X}_1, \dots, \bar{X}_n)$ the conditional expectation is random.

the information given by knowing $\bar{X}_1, \dots, \bar{X}_n$ is denoted F_n

$E[\bar{Y} | \bar{X}_1, \dots, \bar{X}_n] \equiv E[\bar{Y} | F_n]$

What are the properties of the conditional expectation $E[\bar{Y} | F_n]$?

$E[a\bar{Y}_1 + b\bar{Y}_2 | F_n] = a E[\bar{Y}_1 | F_n] + b E[\bar{Y}_2 | F_n]$ (proof same as ordinary ...)

$\bar{Y} \geq 0 \Rightarrow E[\bar{Y} | F_n] \geq 0$ • \bar{Y} is F_n -measurable $\Rightarrow E[\bar{Y} | F_n] = \bar{Y}$ (because we know the value of \bar{Y})

Random variable Z is F_n -measurable (explainable) if we can say what the value of Z is knowing the information F_n .

ex) $Z = \bar{X}_1 + \dots + \bar{X}_n \Rightarrow Z$ is F_n -measurable.

Z is F_n -measurable $\Rightarrow E[Z\bar{Y} | F_n] = Z E[\bar{Y} | F_n]$ (we know Z)

\bar{Y} independent of $F_n \Rightarrow E[\bar{Y} | F_n] = E[\bar{Y}]$

version (generalization) of

$E[\bar{Y}] = \int_{-\infty}^{\infty} E[\bar{Y} | \bar{X} = x] f_{\bar{X}}(x) dx$

Towering: $E[E[\bar{Y} | F_m] | F_n] = E[\bar{Y} | F_n]$ when $m > n$.

Important!

$E[E[\bar{Y} | F_n]] = E[\bar{Y}] = \int_{-\infty}^{\infty} \dots \int_{-\infty}^{\infty} E[\bar{Y} | \bar{X}_1 = x_1, \dots, \bar{X}_n = x_n] f_{\bar{X}_1, \dots, \bar{X}_n}(x_1, \dots, x_n) dx_1 \dots dx_n$

option which has the correct value, a slot machine that gives 100% back ...

Jensen's inequality

$$E[g(Y) | F_n] \geq g(E[Y | F_n])$$

Consequences of Martingale definition

If $\{X_n\}_{n=0}^{\infty}$ is martingale then a) $E[X_n] = E[X_0]$ is constant (same all the time)

b) $E[X_{m+n} | F_n] = X_n$ for $m \geq 0$.

Proof

b) $E[X_{m+n} | F_n] = E[E[X_{m+n} | F_{m+n-1}] | F_n] = \underbrace{E[X_{m+n-1} | F_n]}_{\substack{\text{greater than } n \\ \text{definition}}} = \dots = E[X_{n+1} | F_n] = X_n$

a) $n=0$ in b) $E[X_m | F_0] = X_0 \Rightarrow E[E[X_m | F_0]] = E[X_0] = E[X_m]$

$\{X_n\}_{n=0}^{\infty}$ submartingale if $E[X_{n+1} | F_n] \geq X_n$

$\{X_n\}_{n=0}^{\infty}$ supermartingale if $E[X_{n+1} | F_n] \leq X_n$

ex) submartingale / supermartingale

Y_1, \dots, Y_n independent r.v with common expectation $E[Y_n] = c$

$X_n = \sum_{i=0}^n Y_i$ martingale if $c=0$

-||- submartingale if $c > 0$

-||- supermartingale if $c < 0$

$$E[X_{n+1} | X_1 = x_1, \dots, X_n = x_n] = E[Y_{n+1} + \sum_{i=1}^n Y_i | Y_1 = x_1, \dots, \sum_{i=1}^n Y_i = x_n] = c + x_n$$

Theorem

$\{X_n\}_{n=0}^{\infty}$ supermartingale $\Rightarrow \{-X_n\}_{n=0}^{\infty}$ submart.

-||- submart \Rightarrow -||- supermart

$\{X_n\}_{n=0}^{\infty}$ sub- and supermart $\Rightarrow \{X_n\}_{n=0}^{\infty}$ martingale

Normally distributed \Rightarrow every linear comb normally distributed.

$$\sum_{i=1}^n a_i (c_i + X_i) = \underbrace{\sum_{i=1}^n a_i c_i}_{\text{constant}} + \sum_{i=1}^n a_i X_i$$

Normally distributed with shifted expectation

19/11-10) $\{X_n\}_{n=0}^{\infty}$ time discrete random process

$E[X_{n+1} | \mathcal{F}_n, X_1] = E[X_{n+1} | \mathcal{F}_n] = X_n$ martingale
 \geq submartingale
 \leq supermartingale

Theorem
Dobbs decomposition

If $\{X_n\}_{n=0}^{\infty}$ is a submartingale then there exists a martingale $\{M_n\}_{n=0}^{\infty}$ and an increasing process $\{A_n\}_{n=0}^{\infty}$ such that $X_n = M_n + A_n$

ex) $X_n = \sum_{i=1}^n Y_i$ where Y_1, Y_2, \dots are independent with common expected value $E[Y_i] = c > 0$.

$E[X_{n+1} | X_1, \dots, X_n] = E[Y_{n+1} + X_n | X_1, \dots, X_n] = E[Y_{n+1}] + X_n = c + X_n > X_n$
↑ independent of history
↑ fixed

$X_n = \sum_{i=1}^n (Y_i - c) + nc$
↑ M_n martingale
↑ zero-mean indep. r.v.

Stopping-times

A stopping time is a IN-valued r.v. T such that $\{T \leq n\}$ is \mathcal{F}_n -measurable, that is, one can tell whether the event $\{T \leq n\}$ happens (ed) or not using S_1, \dots, S_n

ex 51 A gambler has \$100 starting capital and repeatedly plays a slot machine. where at each play the player earns \$5 with probability $\frac{1}{5}$ and loses his \$1 with probability $\frac{4}{5}$ (fair slot machine) Fortune after round n is $S_n = S_0 + \sum_{i=1}^n X_i$ where $S_0 = 100$ and X_i is simple. \$1 gets back \$1 on average. gain. (The fair game Martingale) same as last lecture but starts at 100.

$T_1 = \text{first time at which fortune is } \$200 = \min\{n : S_n = 200\}$

$T_2 = \text{time for ruin} = \min\{n : S_n = 0\}$

$T_3 = \min\{T_1, T_2\} = \text{first time at which either fortune is } \$200 \text{ or ruin} = \min\{n : S_n = 200 \text{ or } S_n = 0\}$

$\{S_n\}_{n=0}^{\infty}$ is martingale $E[S_{n+1} | S_0, S_1, \dots, S_n] = S_n$?

$\{T_1\}, \{T_2\}, \{T_3\}$ can all be checked whether they hold by inspection of S_1, \dots, S_n

$T = \max\{S_n : n \geq 0\} = \max_{n \geq 0} S_n$ is NOT stopping time. (can't tell whether it is the maximum because one doesn't know the future)

Optional stopping theorem

If $\{X_n\}_{n=0}^{\infty}$ is a martingale and T a stopping time, then $E[X_T] = E[X_0]$ (For a martingale)
 $E[X_n] = E[X_0]$

under technical conditions

- 1) $E[T] < \infty$
- 2) $E[|\bar{X}_n|] < \infty = \begin{cases} 1, T > n \\ 0, T \leq n \end{cases}$
- 3) $\lim_{n \rightarrow \infty} E[|\bar{X}_n| I_{\{T > n\}}] = 0$

Application to ex. 5.1

$T_3 =$ first time at which $S_n = 0$ or $S_n = 200$
 $E[S_{T_3}] = E[S_0] = 100$
 $P(\text{ruin}) \cdot 0 + P(200) \cdot 200$ (can only have two values)
 \uparrow
 $1 - p(\text{success}) \Rightarrow P(\text{success getting } 200) \approx \frac{1}{2}$

- 1) $E[T] < \infty$ (by some arguments)
- 2) is satisfied $E[|S_{T_3}|] \leq 200 < \infty$
- 3) $E[|S_n| I_{\{T > n\}}] \rightarrow 0$
 \uparrow
 $\leq 200 \rightarrow 0$

$E[S_{T_1}] = 200 \neq E[S_0] = 100$ (not really correct?! can have 198 and earn 5 \Rightarrow 203)
 $E[S_{T_2}] = 0 \neq E[S_0] = 100$

Chapter 6 Analysis and processing of Random processes.

continuous time martingales

$\{X(t)\}_{t \geq 0}$ $E[X(t) | F_s] = X(s)$ for $s \leq t$ where F_s is the information available from $\{X(r)\}_{r \leq s}$

ex) wiener process

$\{W(t)\}_{t \geq 0}$ is mart, because $E[W(t) | \{W(r)\}_{r \leq s}] = E[W(t) - W(s) + W(s) | \{W(r)\}_{r \leq s}] =$
 $= E[\underbrace{W(t) - W(s)}_0] + W(s)$
 $T =$ first time $W(t) = 200$ or $W(t) = -100$ (stopping time) $1 - p(\text{reach } 200 \text{ first})$
 $0 = E[W(0)] = E[W(t)] = 200 \cdot p(\text{reach } 200 \text{ first}) + (-100) \cdot p(\text{reach } -100 \text{ first})$ $P(\text{reach } 200 \text{ first}) = 1/3$

Continuity, derivation and integration of random processes. $\{X(t)\}_{t \in \mathbb{R}}$

Continuity: $X(t+\epsilon) - X(t) \rightarrow 0$ as $\epsilon \rightarrow 0$ $E[(X(t+\epsilon) - X(t))^2] \rightarrow 0$ as $\epsilon \rightarrow 0$

Derivative: $\frac{X(t+\epsilon) - X(t)}{\epsilon} - X'(t) \rightarrow 0$ as $\epsilon \rightarrow 0$ $E[(\frac{X(t+\epsilon) - X(t)}{\epsilon} - X'(t))^2] \rightarrow 0$ as $\epsilon \rightarrow 0$

Integration (Riemann): $\sum_{i=1}^n X(s_i) (t_i - t_{i-1}) \rightarrow \int_a^b X(s) ds$ when $a = t_0 < t_1 < \dots < t_n = b$ satisfies $\max_{1 \leq i \leq n} t_i - t_{i-1} \rightarrow 0$
 as $n \rightarrow \infty, s_i \in [t_{i-1}, t_i]$ $E[(\sum_{i=1}^n X(s_i) (t_i - t_{i-1}) - \int_a^b X(s) ds)^2] \rightarrow 0$, as $n \rightarrow \infty$

Mean square convergence

There are processes converging in first mode but not in the second! \wedge^2

Autocorrelation function $R_{XX}(s, t) = E[X(s)X(t)]$

say interesting things, but NOT everything

dependence among function values etc.

Autocovariance function $H_{XX}(s, t) = \text{cov}[X(s), X(t)]$

$R_{XX}(s, t) - H_X(s)H_X(t)$

Mean function $H_X(t) = E[X(t)]$

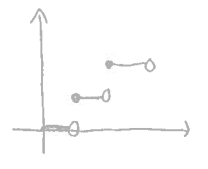
$F_{\bar{X}(t_1), \dots, \bar{X}(t_n)}(x_1, \dots, x_n) = P(\bar{X}(t_1) \leq x_1, \dots, \bar{X}(t_n) \leq x_n)$ in general, to calculate this is impossible! =
 use the above functions to describe the distribution for normal / gaussian processes it is enough!

Continuity

$E[(\bar{X}(t+\epsilon) - \bar{X}(t))^2] = R_{\bar{X}\bar{X}}(t+\epsilon, t+\epsilon) - 2R_{\bar{X}\bar{X}}(t, t+\epsilon) + R_{\bar{X}\bar{X}}(t, t)$

\bar{X} is continuous iff $R_{\bar{X}\bar{X}}$ is continuous

ex) Poisson process



if $\epsilon > 0$, because of stationary increments
 $E[(\bar{X}(t+\epsilon) - \bar{X}(t))^2] = E[\bar{X}(t+\epsilon)^2] = \lambda|\epsilon| + \lambda^2\epsilon^2 \rightarrow 0$ as $\epsilon \rightarrow 0$
 "explanation": probability of jumping in a specific point = 0

\bar{X} is differentiable $\Leftrightarrow R_{\bar{X}\bar{X}}$ is two times differentiable.

If \bar{X} is differentiable with derivative process \bar{X}'

$H_{\bar{X}'}(t) = ?$ $H_{\bar{X}'}(t) = E[\bar{X}'(t)] = E\left[\lim_{\epsilon \rightarrow 0} \frac{\bar{X}(t+\epsilon) - \bar{X}(t)}{\epsilon}\right] = \lim_{\epsilon \rightarrow 0} E\left[\frac{\bar{X}(t+\epsilon) - \bar{X}(t)}{\epsilon}\right] =$

$R_{\bar{X}'\bar{X}'}(s, t) = ?$ $\lim_{\epsilon \rightarrow 0} \frac{H_{\bar{X}'}(t+\epsilon) - H_{\bar{X}'}(t)}{\epsilon} = H_{\bar{X}'}'(t)$ $H_{\bar{X}'}(t) = H_{\bar{X}'}(t)$

$R_{\bar{X}'\bar{X}'}(s, t) = E[\bar{X}'(s)\bar{X}'(t)] = E\left[\lim_{\epsilon \rightarrow 0} \frac{\bar{X}(s+\epsilon) - \bar{X}(s)}{\epsilon} \cdot \lim_{\epsilon \rightarrow 0} \frac{\bar{X}(t+\epsilon) - \bar{X}(t)}{\epsilon}\right] = \lim_{\epsilon \rightarrow 0} \frac{R_{\bar{X}\bar{X}}(s+\epsilon, t+\epsilon) - R_{\bar{X}\bar{X}}(s+\epsilon, t) - R_{\bar{X}\bar{X}}(s, t+\epsilon) + R_{\bar{X}\bar{X}}(s, t)}{\epsilon^2}$
 $= \frac{\partial^2 R_{\bar{X}\bar{X}}(s, t)}{\partial s \partial t}$ $\frac{f(t+\epsilon) - 2f(t) + f(t-\epsilon)}{\epsilon^2} \rightarrow f''(t)$

Integration $E\left[\int_a^b \bar{X}(s) ds\right] \approx E\left[\sum_{i=1}^n \bar{X}(s_i)(t_i - t_{i-1})\right] = \sum_{i=1}^n E[\bar{X}(s_i)](t_i - t_{i-1}) \approx \int_a^b E[\bar{X}(s)] ds$

$\text{cov}\left[\int_a^b \bar{X}(s) ds, \int_a^b \bar{X}(t) dt\right] = \int_a^b \int_a^b \text{cov}[\bar{X}(s), \bar{X}(t)] ds dt$

$E\left[\int_a^b \bar{X}(s) ds \int_a^b \bar{X}(t) dt\right] = \int_a^b \int_a^b R_{\bar{X}\bar{X}}(s, t) ds dt$

p: probability success

25/11-10

$$S_0 = 100 \quad S_n = \sum_{i=1}^n X_i \quad X_i = \begin{cases} 4 \text{ wp } 1/5 \\ -1 \text{ wp } 4/5 \end{cases}$$

$$T = \min\{n : S_n \geq 200 \text{ or } S_n = 0\}$$

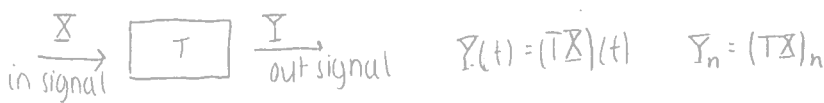
$$100 = E[S_0] = E[S_T] \geq p \cdot 200 + (1-p) \cdot 0 \quad \text{divides: } p \in \left[\frac{100}{200}, \frac{1}{2} \right]$$

\hat{p} proportion of successes from simulations.

$$P = \hat{p} \pm \sqrt{\hat{p}(1-\hat{p})/n} \cdot 4 \quad (\text{standard deviation}) \quad p = \hat{p} \pm \frac{z}{\sqrt{n}} \quad \frac{z}{\sqrt{n}} \approx \frac{1}{1000} \text{ to get a better estimate.}$$

Section 6.3-6.5

wss process $\{X(t)\}_{t \in \mathbb{R}}$ $\{X(n)\}_{n \in \mathbb{Z}}$ linear "device" (invariant in time)



linearity $T(\alpha X_1 + \beta X_2) = \alpha T(X_1) + \beta T(X_2)$
 time-homogeneity (invariant in time) $T(X(t-t_0)) = T(X)(t-t_0)$
 delayed signal

impulse response $h(t) = (T\delta)(t)$ $h(n) = (T\delta)_n$
 Dirac function (distribution) $\delta_n = \begin{cases} 0, n \neq 0 \\ 1, n = 0 \end{cases}$
 $\int_{-\infty}^{\infty} \delta(x) dx = 1$

Any in signal X_n in discrete time can be written $X_n = \sum_{k=-\infty}^{\infty} X_k \delta(n-k)$

$$(TX)_n = T\left(\sum_{h=-\infty}^{\infty} X_h \delta(n-h)\right) = \sum_{h=-\infty}^{\infty} X_h T(\delta(n-h)) = \sum_{h=-\infty}^{\infty} X_h h(n-h) = (X * h)(n) \quad \text{discrete case}$$

$$(TX)(t) = \int_{-\infty}^{\infty} X(s) h(t-s) ds = (X * h)(t) \quad \text{continuous case}$$

wss process is such that $R_{XX}(\tau) = E[X(t)X(t+\tau)]$ doesn't depend on t.
 $H_X = E[X(t)] = \text{constant}$

For the in-signal

is it a wss? yes!

Out-signal $R_{YY}(\tau)$

often assume the mean to be zero

$$H_Y = E[Y(t)] = E\left[\int_{-\infty}^{\infty} X(r) h(t-s) ds\right] = \int_{-\infty}^{\infty} E[X(r)] h(t-s) ds = H_X \int_{-\infty}^{\infty} h(s) ds$$

variable substitution \rightarrow

$$R_{YY}(\tau) = E\left[\int_{-\infty}^{\infty} X(r) h(t-r) dr \int_{-\infty}^{\infty} X(s) h(t+\tau-s) ds\right] = \iint_{-\infty}^{\infty} E[X(r)X(s)] h(t-r) h(t+\tau-s) dr ds$$

$R_{XX}(r-s)$ $r = \hat{r} + t$ $s = \hat{s} + t$

$$= \iint_{-\infty}^{\infty} E[X(\hat{r})X(\hat{s})] h(\hat{r}) h(\hat{s} + \tau) d\hat{r} d\hat{s}$$

because convolutions are involved, one might suspect Fourier transforms to be involved.

$$S_{XX}(\omega) = \int_{-\infty}^{\infty} e^{-j\omega\tau} R_{XX}(\tau) d\tau \quad \text{Fourier transform of } R_{XX} \text{ called } \underline{\text{power spectral density}} \text{ of } R_{XX}(\tau)$$

$$R_{XX}(\tau) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{j\omega\tau} S_{XX}(\omega) d\omega$$

all frequencies are equally important in white noise!

white noise

$$R_{XX}(\tau) = \sigma^2 \delta(\tau)$$

$$S_{XX}(\omega) = \sigma^2$$

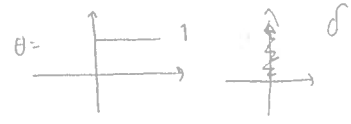
Delta function, Dirac's δ , dirac function, delta distribution, dirac distribution, continuous time version of Kronecker's delta

$$\delta: \mathbb{R} \rightarrow \mathbb{R} \quad \delta(t) = 0, t \neq 0$$

$$\int_{-\infty}^{\infty} g(t) \delta(t) dt = g(0)$$

$$\delta(t) = \theta'(t)$$

filter function.



$$S_{YY}(\omega) = H(\omega) \overline{H(\omega)} S_{XX}(\omega) = |H(\omega)|^2 S_{XX}(\omega) \quad H(\omega) = \int_{-\infty}^{\infty} e^{-j\omega t} h(t) dt$$

$$\overline{H(\omega)} = \int_{-\infty}^{\infty} e^{j\omega t} h(t) dt = \int_{-\infty}^{\infty} e^{-j\omega t} h(-t) dt$$

$$S_{XX}(\Omega) = \sum_{h=-\infty}^{\infty} e^{-j\Omega h} R_{XX}(h)$$

$$R_{XX}(\tau) = \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{j\Omega\tau} S_{XX}(\Omega) d\Omega$$

$$H(\Omega) = \sum_{h=-\infty}^{\infty} e^{-j\Omega h} h(h)$$

$$S_{YY}(\Omega) = |H(\Omega)|^2 S_{XX}(\Omega)$$

two wss processes

$$R_{XY}(\tau) = E[X(t)Y(t+\tau)] \quad \{X(t)\}_{t \in \mathbb{R}}, \{Y(t)\}_{t \in \mathbb{R}} \text{ wss (says something about dependence between } X \text{ and } Y)$$

$$S_{XY}(\omega) = \int_{-\infty}^{\infty} e^{-j\omega\tau} R_{XY}(\tau) d\tau$$

$$R_{X, h * \delta} = E[X(t) \int_{-\infty}^{\infty} X(s) h(t+\tau-s) ds] = \int_{-\infty}^{\infty} h(t+\tau-s) R_{XX}(t-s) ds = \left[\begin{matrix} \hat{t} = t-s & s = +\infty \rightarrow \hat{t} = -\infty \\ d\hat{t} = -ds & s = -\infty \rightarrow \hat{t} = \infty \end{matrix} \right] =$$

$$Y = h * X$$

$$= - \int_{-\infty}^{\infty} h(\tau + \hat{t}) R_{XX}(\hat{t}) d\hat{t} = \int_{-\infty}^{\infty} h(\tau + \hat{t}) R_{XX}(\hat{t}) d\hat{t} = \left[\begin{matrix} \hat{t} = -\hat{t} & R_{XX}(\hat{t}) = R_{XX}(-\hat{t}) \\ R_{XX} \text{ symmetric} \end{matrix} \right] = \int_{-\infty}^{\infty} h(\tau - \hat{t}) R_{XX}(\hat{t}) d\hat{t} =$$

$$= (h * R_{XX})(\tau) \quad S_{X, h * \delta}(\omega) = H(\omega) S_{XX}(\omega)$$

126/17-10)

Convolution (faltung)

continuous time $f, g: \mathbb{R} \rightarrow \mathbb{R}$ $f * g(t) = \int_{-\infty}^{\infty} f(s)g(t-s)ds = \int_{-\infty}^{\infty} f(t-s)g(s)ds$

Discrete time $f, g: \mathbb{Z} \rightarrow \mathbb{R}$ $f * g(n) = \sum_{h=-\infty}^{\infty} f(h)g(n-h) = \sum_{h=-\infty}^{\infty} f(n-h)g(h)$

ex) X and Y independent random variables with pdf f_X, f_Y

$f_{X+Y}(z) = \int_{-\infty}^{\infty} f_X(r)f_Y(z-r)dr = f_X * f_Y(z)$

Fourier transforms

continuous time $f: \mathbb{R} \rightarrow \mathbb{R}$ $\hat{f}(\omega) = \int_{-\infty}^{\infty} e^{-j\omega x} f(x)dx$

inverse transform $f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{j\omega x} \hat{f}(\omega) d\omega$

Discrete time: $f: \mathbb{Z} \rightarrow \mathbb{R}$ $\hat{f}(\omega) = \sum_{h=-\infty}^{\infty} e^{-j\omega h} f(h)$

inverse transform $f(h) = \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{j\omega h} \hat{f}(\omega) d\omega$

$(f * g)^\wedge(\omega) = \hat{f}(\omega)\hat{g}(\omega)$

Proof (continuous time)

$(f * g)^\wedge(\omega) = \int_{-\infty}^{\infty} e^{-j\omega x} \left[\int_{-\infty}^{\infty} f(y)g(x-y)dy \right] dx = \int_{-\infty}^{\infty} e^{-j\omega y} \left[\int_{-\infty}^{\infty} e^{-j\omega(x-y)} g(x-y) dx \right] f(y) dy = \hat{g}(\omega)\hat{f}(\omega)$

Impulses - delta function

continuous time $\delta: \mathbb{R} \rightarrow \mathbb{R}$ $\delta(x) = 0 \quad x \neq 0$ $\int_{-\infty}^{\infty} g(x)\delta(x)dx = g(0)$



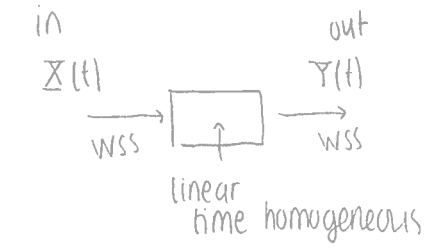
Discrete time $\delta: \mathbb{Z} \rightarrow \mathbb{R}$ $\delta(h) = \begin{cases} 1, & h=0 \\ 0, & h \neq 0 \end{cases}$

ex) white noise

continuous time: random process $\{w(t)\}_{t \in \mathbb{R}}$ that is zero-mean, wss with $R_{ww}(\tau) = \sigma^2 \delta(\tau)$

Discrete time: random process $\{w(h)\}_{h \in \mathbb{Z}}$ that is zero-mean wss with $R_{ww} = \sigma^2 \delta(h)$

Linear system (filter)



$Y(t) = (T X)(t)$

$h(t) = (T \delta)(t) \Rightarrow Y(t) = (h * X)(t)$

impulse response

$R_{YY}(\tau) = h * h(-x) * R_{XX}(\tau)$

$H_{\tau} = H_X \int_{-\infty}^{\infty} h(t)dt$

PSD (power spectral density) $S_{XX}(\omega) = (R_{XX})'(\omega)$

filter function $H(\omega) = \hat{h}(\omega)$

$$S_{ZY}(\omega) = (R_{ZY})'(\omega) = \hat{h}(\omega)(\hat{h}(-1))(\omega) S_{XX}(\omega) = |H(\omega)|^2 S_{XX}(\omega)$$

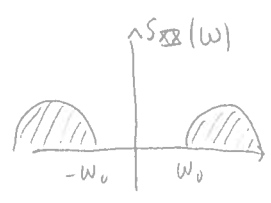
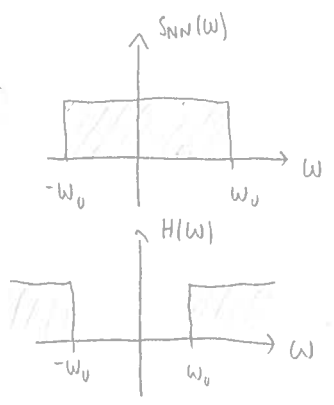
$$H(\omega) \cdot H^*(\omega)$$

ex) Send random wss signal $X(t)$ on noisy channel. we receive $Y(t) = X(t) + N(t)$
 N is wss zero-mean, independent of X

We want to construct a filter that removes noise "as good as possible"



X and N zero-mean wss $R_{XX}(\tau)$ $R_{NN}(\tau)$
 $S_{XX}(\omega)$ $S_{NN}(\omega)$



Wiener filter (the best filter for the example)
 $H(\omega) = \frac{S_{XX}(\omega)}{S_{XX}(\omega) + S_{NN}(\omega)}$

X is wss process with autocorrelation function R_{XX}

$$R_{XX}(\tau) = E[X(t)X(t+\tau)]$$

- 1) $R_{XX}(\tau) = R_{XX}(-\tau)$
- 2) $R_{XX}(0) = E[X(t)^2] \geq 0$
- 3) $|R_{XX}(\tau)| \leq R_{XX}(0)$

Proof 3

$$0 \leq E[(X(t) - X(t+\tau))^2] = 2(R_{XX}(0) - R_{XX}(\tau))$$

$$S_{XX}(\omega) = (R_{XX})'(\omega) = \int_{-\infty}^{\infty} e^{-j\omega\tau} R_{XX}(\tau) d\tau$$

$S_{XX}(\omega)$ real valued non-negative

$$S_{XX}(\omega) = S_{XX}(-\omega)$$

$$R_{XX}(0) = E[X(t)^2] = \frac{1}{2\pi} \int_{-\infty}^{\infty} S_{XX}(\omega) d\omega$$

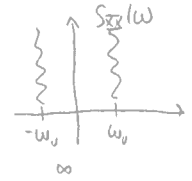
$$R_{XX}(\tau) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{j\omega\tau} S_{XX}(\omega) d\omega$$

ex) $R_{XX}(\tau) = \sigma^2 \delta(\tau)$ (white noise) $\Rightarrow S_{XX}(\omega) = \sigma^2$
 equal amount of all frequencies

$$X(t) = \sum \cos(\omega_0 t) \Rightarrow R_{XX}(\tau) = \cos(\omega_0 \tau)$$

zero-mean
unit variance

$$S_{XX}(\omega) = \pi [\delta(\omega - \omega_0) + \delta(\omega + \omega_0)]$$



ex) $R_{XX}(\tau) = e^{-|\tau|}$
 $S_{XX}(\omega) = \int_{-\infty}^{\infty} e^{-j\omega\tau} R_{XX}(\tau) d\tau =$

$$\int_0^{\infty} e^{-j\omega\tau} e^{-\tau} d\tau + \int_{-\infty}^0 e^{-j\omega\tau} e^{\tau} d\tau = \left[\frac{e^{-(1+j\omega)\tau}}{-(1+j\omega)} \right]_0^{\infty} + \left[\frac{e^{(1-j\omega)\tau}}{1-j\omega} \right]_{-\infty}^0 = \frac{1}{1+j\omega} + \frac{1}{1-j\omega} = \frac{2}{1+\omega^2}$$

$$R_{xx}(\tau) = \frac{2}{1+\tau^2} \Rightarrow S_{xx}(\omega) = 2\pi e^{-|\omega|}$$

If $X(t)$ and $Y(t)$ are WSS, then $R_{xy}(\tau) = E[X(t)Y(t+\tau)]$

$$S_{xy}(\omega) = \int_{-\infty}^{\infty} e^{-j\omega\tau} R_{xy}(\tau) d\tau$$

$$R_{yX}(\tau) = (h * R_{xx})(\tau) \quad S_{yX}(\omega) = H(\omega) S_{xx}(\omega)$$

Derivation of Wiener filter (not in book)

Select to minimize $E[(z(t) - \hat{X}(t))^2] = E[(h * Y(t) - \hat{X}(t))^2] = E[(h * X(t) + h * N(t) - \hat{X}(t))^2] =$

$$R_{h*X}, h*X(0) + R_{h*N, h*N}(0) + R_{xx}(0) + \underbrace{2R_{h*X, h*N}}_{=0} - \underbrace{2R_{h*N, \hat{X}}(0)}_0 =$$

$$= E\left[\int_{-\infty}^{\infty} h(t-s)N(s)ds \hat{X}(t)\right] = \frac{1}{2\pi} \int_{-\infty}^{\infty} (|H(\omega)|^2 S_{xx}(\omega) + |H(\omega)|^2 S_{NN}(\omega) + S_{xx}(\omega) - 2H(\omega)S_{xx}(\omega)) d\omega$$

could lift out the integral

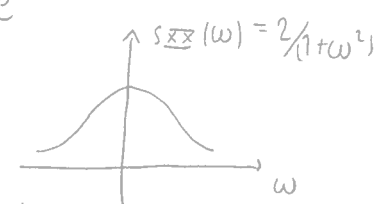
Differentiate with respect to H : $2HS_{xx} + 2HS_{NN} - 2S_{xx} = 0 \Rightarrow H(\omega) = \frac{S_{xx}(\omega)}{S_{xx}(\omega) + S_{NN}(\omega)}$

The reason for skipping the absolute value is that $E[(z(t) - \hat{X}(t))^2]$ is always real.

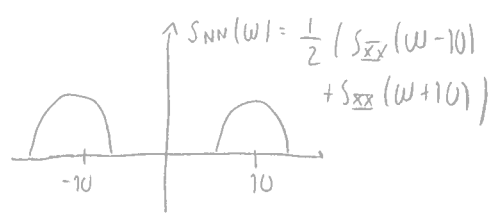
Computational problem

$\{X(t)\}_{t \in \mathbb{R}}$ OU-process: Gaussian process with zero-mean, $R_{XX}(\tau) = e^{-|\tau|}$

$\{N(t)\}_{t \in \mathbb{R}}$ Gaussian noise zero-mean

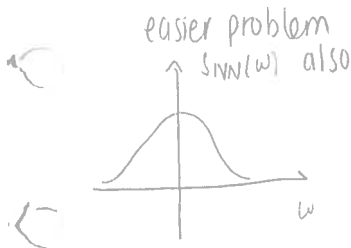


$S_{NN}(\omega) = \frac{1}{2} (S_{XX}(\omega-10) + S_{XX}(\omega+10))$



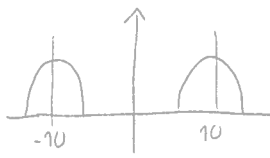
$Y(t) = X(t) + N(t)$

$H(\omega)$ filter. =



"fool" the noise move the frequency content

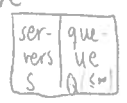
$\hat{X}(t) = \cos(\theta + \omega(t)) X(t)$



High pass filter.

$n = Q + S (\leq \infty)$

customers arrive



FIFO (first in first out) fair queue

$X(t) = \frac{\text{number of customers in queue system}}{\text{(served customers + those queuing)}}$

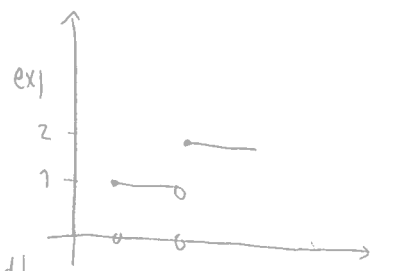
interarrival times between customers.

$\exp(\lambda)$ -distributed (existing in nature - the most important example)

service times $\exp(H)$ -distributed

$X(0)$

Required to specify the queuing system



queue process $\{X(t)\}_{t \geq 0}$ (Markov process, continuous time, discrete valued)

Markov chain in continuous time.

M.C. in continuous time is the POISSON PROCESS $\{X(t)\}_{t \geq 0}$ with intensity λ .

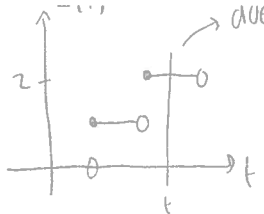
$P\{X(t) \leq x | X(t_1), \dots, X(t_n)\} = P\{X(t) - X(t_n) \leq x - X(t_n) | X(t_n)\} = P\{X(t) \leq x | X(t_n)\}$

Lack of memory property.

independent increment doesn't depend on history. and $X(t_n)$ depends only on itself

for $0 \leq t_1 < \dots < t_n < t$

Theorem A continuous r.v. $T > 0$ has the lack of memory property $P\{T > t+s | T > s\} = P\{T > t\}$ iff T is exponentially distributed.



does it matter how long time has elapsed of the interval?
Proof
 \Leftrightarrow The exponential distribution satisfies the property.

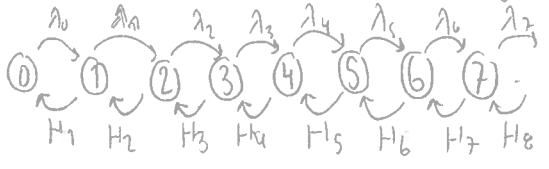
$$P(T > t+s | T > s) = \frac{P(T > t+s, T > s)}{P(T > s)} = \frac{\exp(-\lambda(t+s))}{\exp(-\lambda s)} = \exp(-\lambda t) = P(T > t)$$

$\Rightarrow P(T > t+s) = P(T > t)P(T > s)$ the only solution to this equation is the exponential distribution.

(whatever Markov chain one has, the time inbetween happenings has to be exponentially distributed)

$\{X(t)\}_{t \geq 0}$ with discrete values is MC iff it stays independent exp-distributed times at its different discrete values.

ex) Birth-death process $\{X(t)\}_{t \geq 0}$ (the by far most important MC)

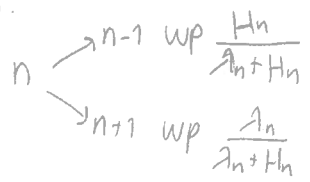


very useful. Poisson process special case, $\lambda_i = \lambda, \mu_i = 0$. could be finite if one of the λ 's equals to 0.

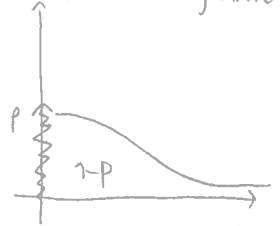
If $X(t) = n$, then we wait $\min(\exp(\lambda_n), \exp(\mu_n))$

distribution of minimum of two independent exponential distributions.

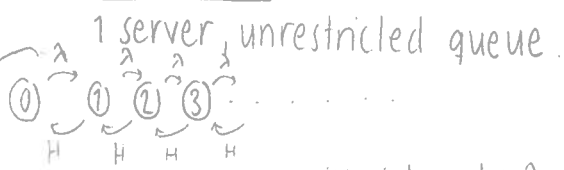
$$P(\min(B, D) > t) = P(B > t) \cdot P(D > t) = e^{-\lambda_n t} e^{-\mu_n t} = P(\exp(\lambda_n + \mu_n) > t)$$



w - waiting time for service. Markov arrivals and service time.

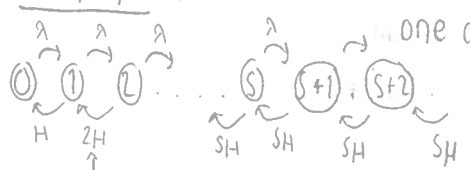


$M/M/1/\infty$ 1 server

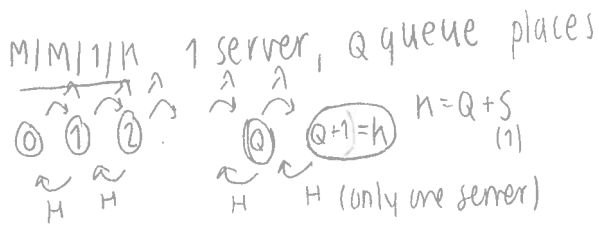


1 server, unrestricted queue. Because the arrival process with intensity λ

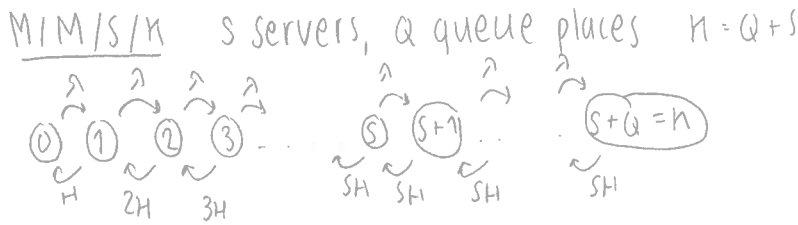
s servers $M/M/s/\infty$ unrestricted queue



one and the same arrival process. because more servers are active



In the book k is total capacity of system, that is the total number of servers + queueing places



$P_n(t) = P(\sum(t) = n)$ how the probability of being in n changes.

$0 = \begin{cases} P_n'(t) = -(\lambda_n + \mu_n)P_n(t) + \mu_{n+1}P_{n+1}(t) + \lambda_{n-1}P_{n-1}(t) & n \geq 1 \\ P_0'(t) = -\lambda_0 P_0(t) + \mu_1 P_1(t) & \end{cases}$

 (comes from above) (comes from above)

Stationary distribution. (The probability of being in n shouldn't change in time.)

$P_n(t) = P_n = \frac{\lambda_0 \dots \lambda_{n-1}}{\mu_1 \dots \mu_n} \cdot C$

 any constant times this works, the sum over p_n has to be 1

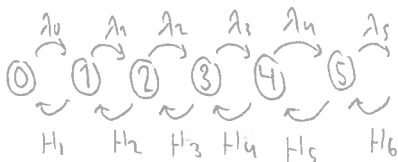
verification

$$-(\lambda_n + \mu_n) \frac{\lambda_0 \dots \lambda_{n-1}}{\mu_1 \dots \mu_n} + \mu_{n+1} \frac{\lambda_0 \dots \lambda_n}{\mu_1 \dots \mu_{n+1}} + \lambda_{n-1} \frac{\lambda_0 \dots \lambda_{n-2}}{\mu_1 \dots \mu_{n-1}} = 0$$

$$-\frac{\lambda_0 \dots \lambda_n}{\mu_1 \dots \mu_n} - \frac{\lambda_0 \dots \lambda_{n-1}}{\mu_1 \dots \mu_{n-1}} + \frac{\lambda_0 \dots \lambda_n}{\mu_1 \dots \mu_n} + \frac{\lambda_0 \dots \lambda_{n-1}}{\mu_1 \dots \mu_{n-1}}$$

3/12-10 Chapter 9 Queues

Birth-death process $\{\sum(t)\}_{t \geq 0}$



spend time in state n according to $\min(\exp(\lambda_n), \exp(\mu_n))$
 $= \exp(\lambda_n + \mu_n)$ go to $n-1$ wp $\frac{\mu_n}{\lambda_n + \mu_n}$
 $n+1$ wp $\frac{\lambda_n}{\lambda_n + \mu_n}$

Usually either $\sum(t)=0$ or $\sum(t)$ has the stationary distribution (steady-state)

$$P(\sum(t) = n) = \frac{\prod_{i=1}^n \lambda_{i-1}}{\sum_{n=0}^{\infty} \prod_{i=1}^n \lambda_{i-1}} = \frac{\lambda_0 \dots \lambda_{n-1}}{\mu_1 \dots \mu_n} \cdot C$$

M/M/1 one server, infinitely many queue places

$\lambda_n = \lambda, \mu_n = \mu$ under steady-state.

 $L = E\{\text{number of customers in queue - whole system}\}$

 $L_q = E\{\text{waiting in queue}\}$

 $L_s = E\{\text{being served}\}$

 $W = E\{\text{Amount of time a customer spends in whole system}\}$

Balance equation eq (9.2) $L = \lambda / \mu$

$N_q = E\{\text{amount of time a customer spends queuing}\} = W - W_s$ (total time in system = queuing time + waiting time)
 $N_s = E\{\text{--- being served}\} = E[\exp(H)] = \frac{1}{H}$

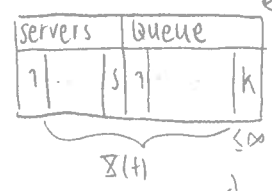
$L = E[X(H)] = \sum_{n=0}^{\infty} n p_n$ stat. distribution. $L_q = \lambda W_q$ $L_s = \lambda W_s$

M/M/1 1 server, infinitely many queue places
 $\lambda_n = \lambda$ $\mu_n = H$

M/M/s s servers, infinitely many queue places
 $\lambda_n = \lambda$, $\mu_n = \min(n, s)H = \begin{cases} nH, & n \leq s \\ sH, & n > s \end{cases}$

M/M/s/k s servers, $k = s + a$ total number of places in queue, $Q = \text{number of queue places}$ $< \infty$.
 $\lambda_n = \begin{cases} \lambda, & n \leq k-1 \\ 0, & n \geq k \end{cases}$ $\mu_n = \min(n, s)H$

queue system Poisson process with intensity λ



$X(t)$ number of busy places. (total, servers + queue)
 $L = L_q + L_s$

M/M/1



$P_n = \left(\frac{\lambda}{H}\right)^n \left(1 - \frac{\lambda}{H}\right)$ $\lambda < H$ $L = \frac{\lambda}{H - \lambda}$
 $L = \sum_{n=0}^{\infty} n \left(\frac{\lambda}{H}\right)^n \left(1 - \frac{\lambda}{H}\right) = \frac{\lambda/H}{(1 - \lambda/H)^2} \left(1 - \frac{\lambda}{H}\right) = \frac{\lambda}{H - \lambda}$

$\frac{1}{-x^2} = \frac{d}{dx} \left(\frac{1}{1-x} - 1\right) = \frac{d}{dx} \sum_{n=1}^{\infty} x^n = \sum_{n=1}^{\infty} n x^{n-1}$

$W = L/\lambda = \frac{1}{H - \lambda}$ $W_q = \frac{L}{\lambda} - \frac{1}{\lambda} = \frac{1}{H - \lambda} - \frac{1}{H} = \frac{\lambda}{(H - \lambda)H}$

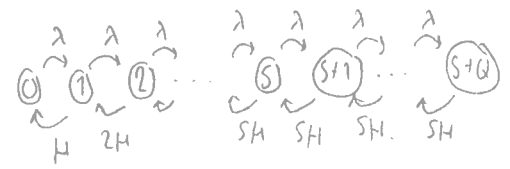
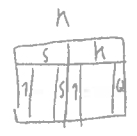
Stochastic differential equations
 $dX(t) = H(X(t)) dt + \sigma(X(t)) dW(t)$

M/M/s/k

$\exp(\lambda)$ - times between arrivals
 $\exp(H)$ - service times
s servers

$k = Q + s$ total places in queue system where $Q = \text{number of places in queue}$.

Poisson with intensity λ



$\sum_{n=0}^N x^n = \frac{1 - x^{N+1}}{1 - x}$

$P_n = \begin{cases} \frac{\lambda^n}{H^n (n!)} / \sum_{n=0}^s \frac{\lambda^n}{H^n (n!)} & n \leq s \\ \frac{\lambda^n}{H^n s! s^{n-s}} / \sum_{n=0}^s \frac{\lambda^n}{H^n (n!)} + \sum_{n=s+1}^{s+Q} \frac{\lambda^n}{H^n s! s^{n-s}} & n = s+1, \dots, s+Q \end{cases}$